

BIRDS Bus Open-Source Webinar

LOW GSD IMAGING SYSTEM PAYLOAD FOR ASEANSAT 1U-SIZED CUBESAT APPLICATION

By Fatimah Zaharah Ali, PhD Universiti Teknologi MARA (UiTM), Malaysia

29th January 2025





CONTENT

CAM MISSION BACKGROUND

O2

MISSION
OPERATION

PROPERTIES AND ATTRIBUTES





BACKGROUND OF CAM MISSION

CAM Mission Statement:

- CubeSat provides low ground resolution imageries due to limitation in selecting suitable imaging sensor.
- With the technology advancement in optical design, ground resolution can be improved.

CAM Mission Objective:

 To capture optimal ground resolution image, store the image onboard and transmit it to ground station.





MISSION REQUIREMENT

Functional Requirements:

- Performance: The satellite shall obtain optimal ground resolution imagery.
- Coverage: The coverage size depends on the amount of viewing angle.
- Timeliness: Satellite shall downlink image packets for every available pass.

Mission Mode:

Single shot

Mission Executions:

Upon command image capturing





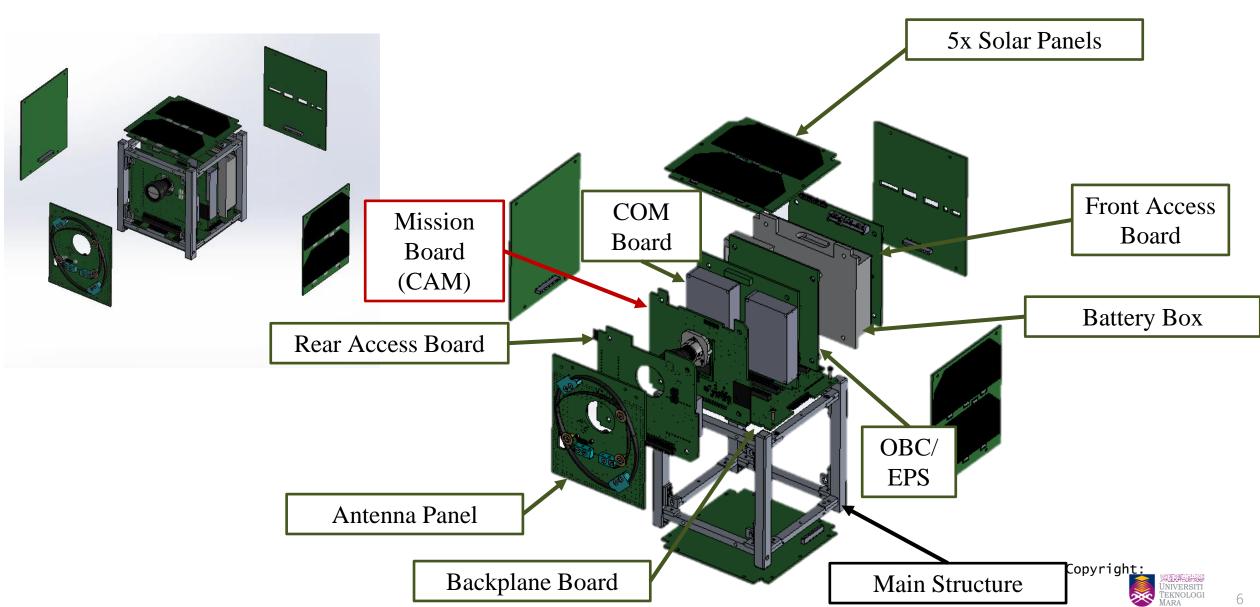
STAGING GOALS

SUCCESS LEVEL	CRITERIONS	
Minimum	Takes image(s).	
Medium	Takes image(s) of Earth.	
Full	Takes image(s) of Earth with optimal ground resolution.	
Extra	Takes image(s) of each of the participating countries with optimal ground resolution.	



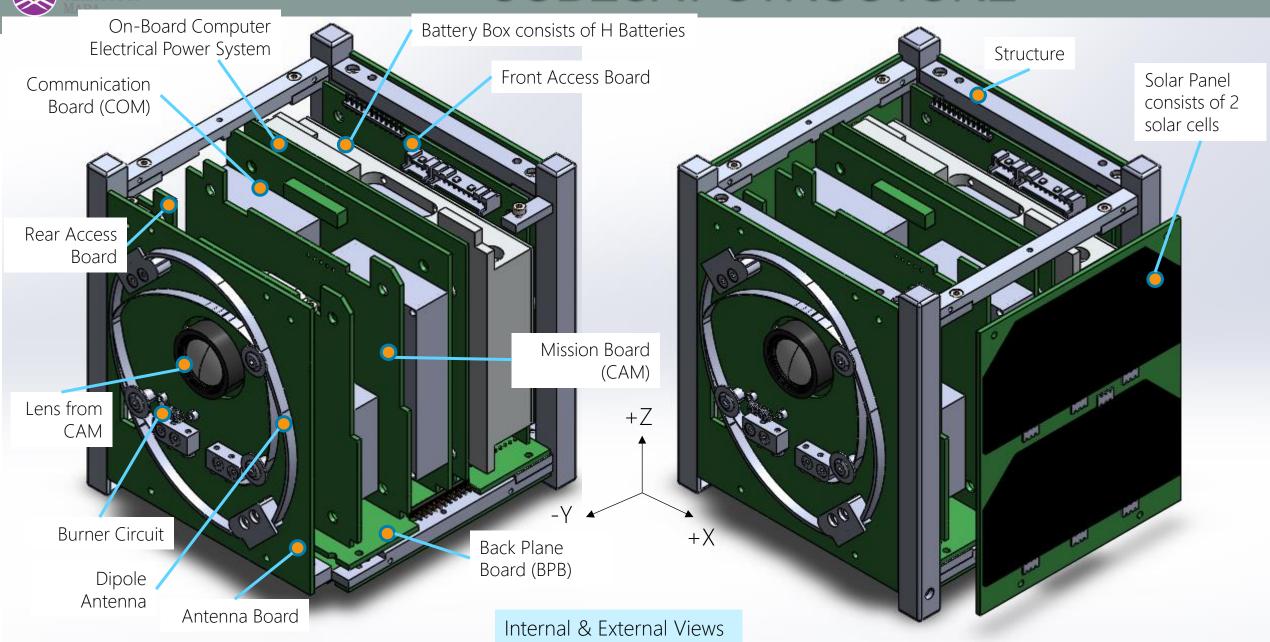


ASEANSAT CUBESAT





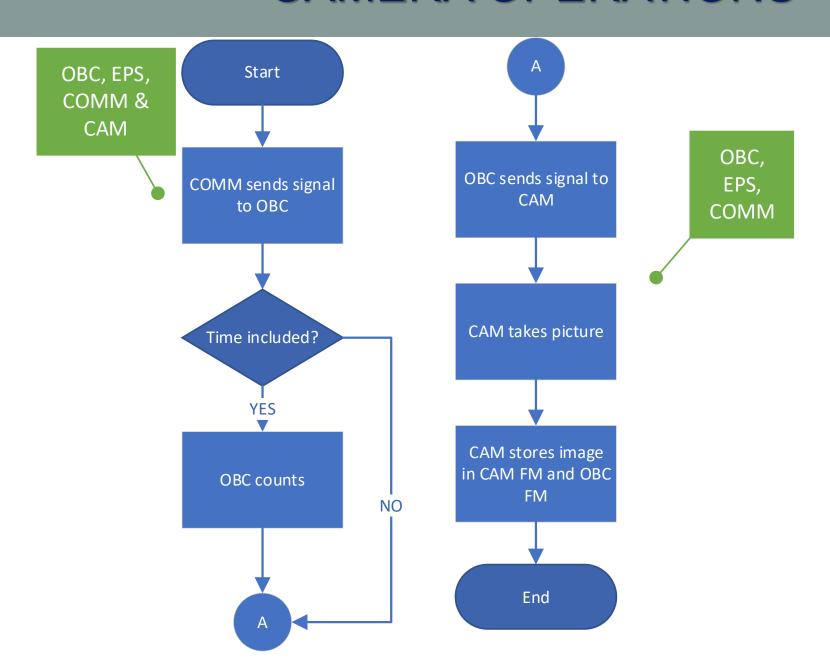
CUBESAT STRUCTURE





CAMERA OPERATIONS

COMMAND MODE

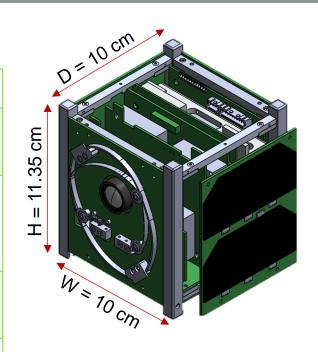






CAMERA MISSION CHARACTERISTICS

		CubeSat
Mass	≤ 50 – 66.5 g (5% lighter) [23] ≤ 100 – 133 g (10% lighter) (BIRDS)	1 – 1.33 kg
Size (W x D x H)	≤ 5 mm x 5 mm x 5.675 mm (5% smaller) ≤ 10 mm x 10 mm x 11.35 mm (10% smaller)	10 cm x 10 cm x 11.35 cm
Power Consumption	0.1 – 0.25 W [32] (depends on power budget calculation)	1 – 2.5 W [16]
Interface	SPI, UART, I2C	UWE-3



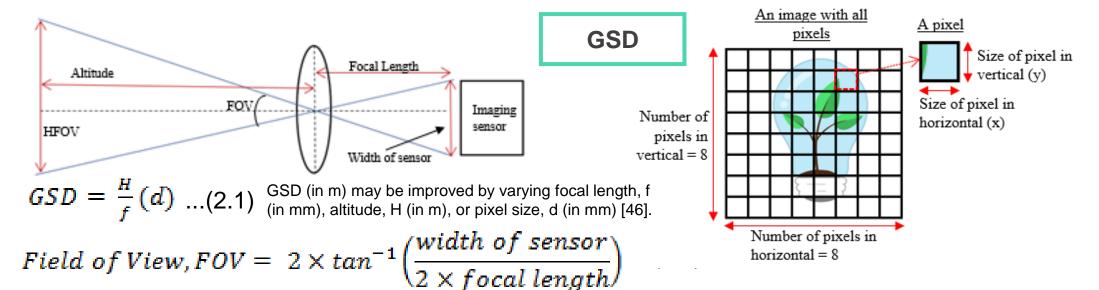
Other technical requirement:

- Temperature range: -40 °C to +50 °C
 - Compatible interface
 - Operating Voltage: 3.3 5 V
 - Compatible & convenience features





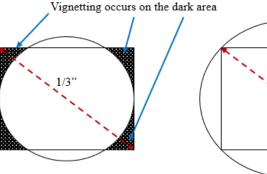
THEORITICAL CALCULATION



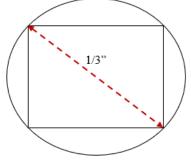
Horizontal Field of View, HFOV = $2 \times altitude \times tan\left(\frac{FOV}{2}\right)$...(3.2)

Lens:

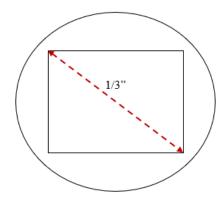
- Mount type
- Optical format



1/4" optical lens mounted on 1/3" imaging sensor



1/3" optical lens mounted on 1/3" imaging sensor



1/2" optical lens mounted on 1/3" imaging sensor



Example of Imagery with Vignetting

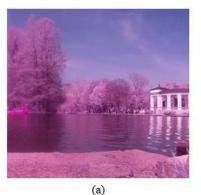
Effect. Source from [32]



IR FILTER

Filter:

VIS = 465 nm to 630 nmIR = 700 nm to 1 mm





Source from furulevi

Incident Imaging light sensor Objective Optical 1ens filter (a) Incident • Imaging light sensor Objective Optical filter

1ens

(b)

UiTMSAT-2:

- Resolution: 2592x1944 pixels array (5 MP)
- Spatial: GSD ~16 m @ 400 km
- Spectral: RGB (λ : 0.4 0.7 nm)
- Radiometric: 8 10 bits image data
- Temporal: $4 \sim 6 \text{ times/day}$ (6~8 minutes/pass)
- Swath: FOV ~6° (41.5 x 31 km)
- Size ~1.152 MB
- JPEG compression

Image Data

Image Size (in bytes, B) = Array Size \times Bit Depth \times Channel ...(3.6)

Data Rate
$$\left(in^{bytes}/_{sec}, Bps\right) = Clock Rate (MHz) \times \sum bytes ...(3.9)$$





SENSOR SELECTION

IR Cut Filter

Material: Glass

ArduCam OV5642 5MP

- Optical format
 - Lens format = ½"
 - Lens mount = CS or M12

I 5 mm

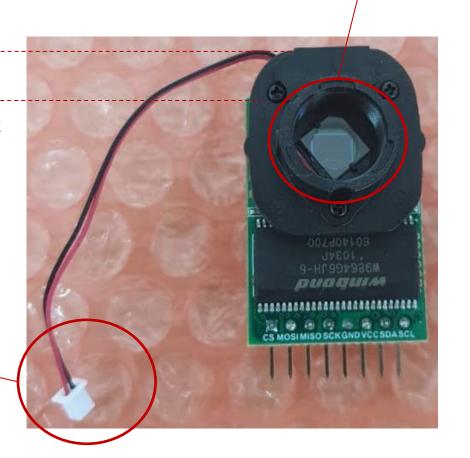
∴ Total height

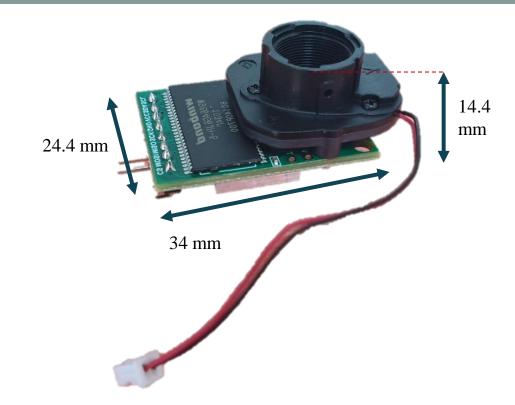
= 39 mm

Power Requirement for IR Cut Filter:

Current: 58~207mA

Voltage: 3.5V~12V





Mass = 8.1g (without lens)





SENSOR SELECTION

Model	CMS-V	FFS-U3- 16S2M-S /FFS-U3- 16S2M- S(SONY IMX296)	FFY-U3-16S2C- S (SONY IMX296)	OV5642
Company	SILIOS Tech	FLIR	FLIR	ArduCam
Spectral Range	Color bands	Monochrome	Color	RGB
Spatial Resolution	-			
Array size (MP)	1.3	1.58/1.6	1.6	5
Power (W)	4.5	1.5/2.2	2.2	1
Size (mm) W x D x H	52 x 52 x 22	27x27x14	27x27x14.5	34x24x30
Volume (mm ³)	59488	10206	10570.5	24480
Weight (g)	59	20	20	20
Interface	USB 3.0	USB3.1	USB3.1	SPI,UART



LENS SELECTION

ArduCam Lens

- Lens format = 1/1.7"
- Lens mount = M12
- FL = 35 mm
- $FOV = 8^{\circ} (H)$
- Dimension: Φ22×29.3mm
- Weight: 15.4g (measured using scale)

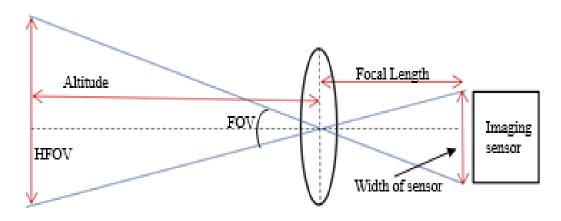






CAMERA ATTRIBUTES

Parameter	VGA	HD	5 MP	
Altitude, H		400 km		
Sensor Size (W x H)	3.6 x 2.7 mm			
Pixel Size, d (W x H)				
Focal length, f				
GSD*	16 m	16 m	16 m	
Effective FOV (Viewing Angle)*	1.5°	4.5°	6º	
HFOV x VFOV*	10.24 x 7.68 km	30.71 x 17.28 km	41.47 x 31.10 km	



Acronym:

VGA – Video Graphics Array
HD – High definition
GSD – Ground Sampling Distance
FOV – Field of View
HFOV – Horizon
VFOV – Vertical FOV



LENS ATTRIBUTES



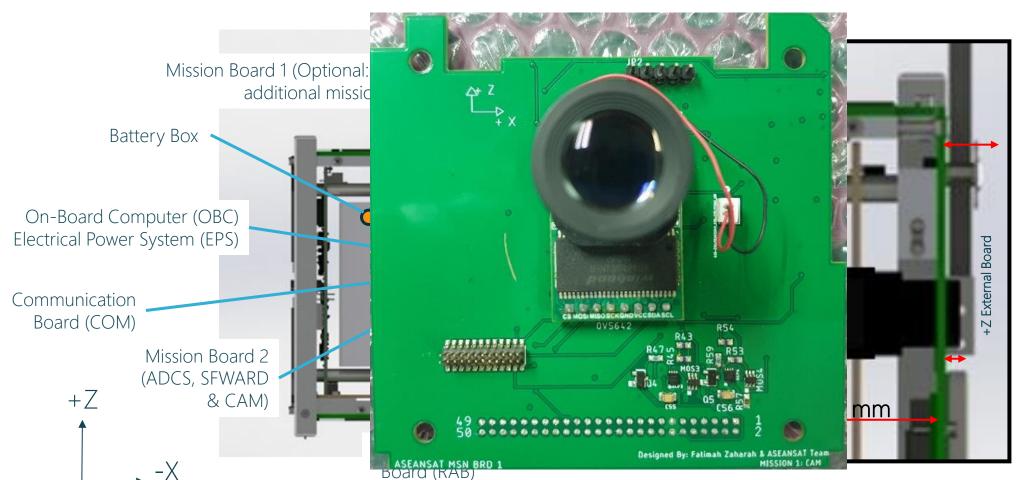




Focal Length	35 mm	25 mm	4.9 mm
Altitude, H		400 km	
Sensor Size (W x H)		3.6 x 2.7 mm	
Pixel Size, d (W x H)		1.4 x 1.4 μm	
GSD*	16 m	22.4 m	114.29 m
FOV*	5.94°	8.30°	40.64°
HFOV x VFOV*	41.47 x 31.10 km	58.01 x 43.55 km	296.23 x 222.17 km
Weight of Lens	15.4 g	8.2 g	1.2 g
Total Weight (with sensor)	23.5 g	16.3 g	6.7 g
Mechanical Size	Ф22×29.3mm	Φ17×21mm	Ф13.8×12.73mm



CAM BOARD



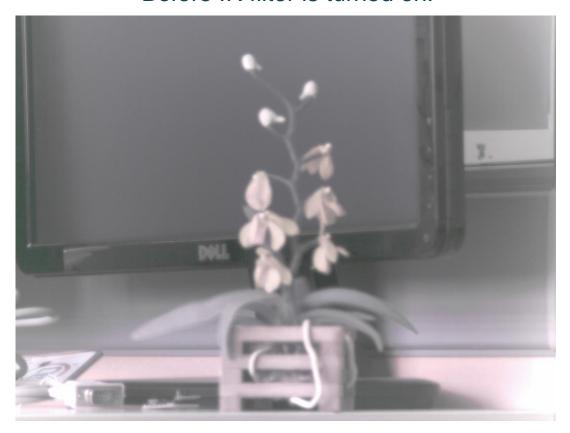
6.5mm
(allowable absolute maximum extrusion)

2.5mm (nominal extrusion for camera lens)

(Mission board to external board)



Before IR filter is turned on.

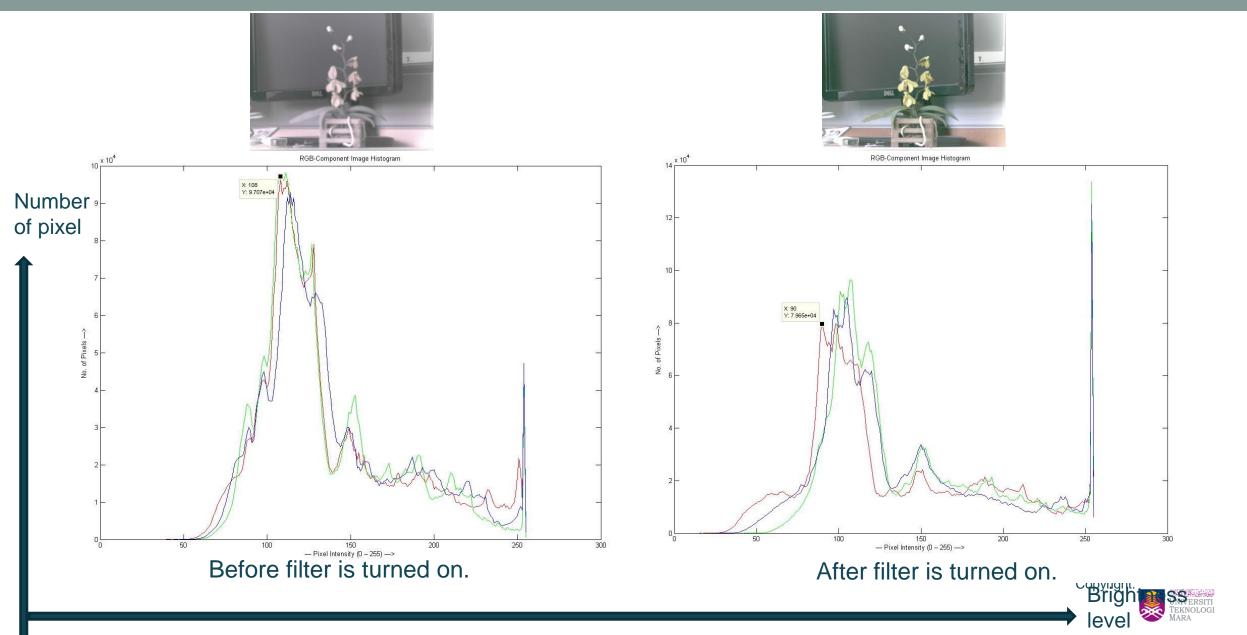


After IR filter is turned on.











SNR Measurement

$$SNR = \frac{\mu}{\sigma}$$

μ: average value of the brightness level

σ: standard deviation of the brightness



Without IR Cut Filter

SNR = 29.4216 dB



With IR Cut Filter

SNR = 31.5173 dB

SNR improved with application of IR Cut Filter. IR ray has become the noise to the image and reduced the accuracy of RGB color distributions.

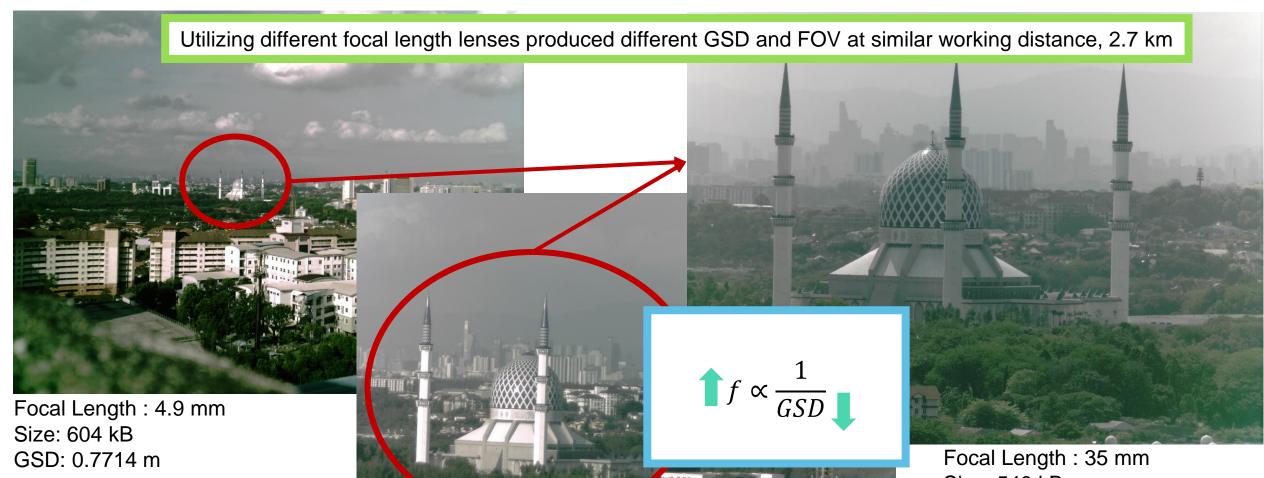


OV5642 with 4.9 mm EFL default lens.









Focal Length: 25 mm

Size: 548 kB

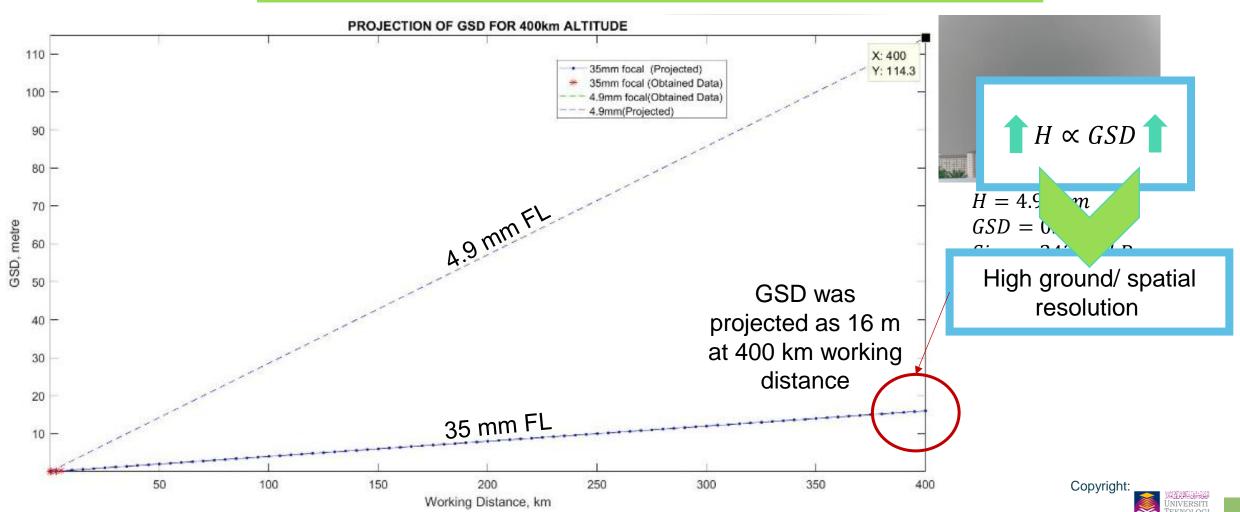
GSD: 0.1512 m

Size: 540 kB GSD: 0.108 m











THANK YOU

Fatimah Zaharah Ali, PhD

Universiti Teknologi MARA (UiTM), Malaysia

fatimah zaharah@uitm.edu.my

+60134900075

