



# Power Budget for IU Satellite

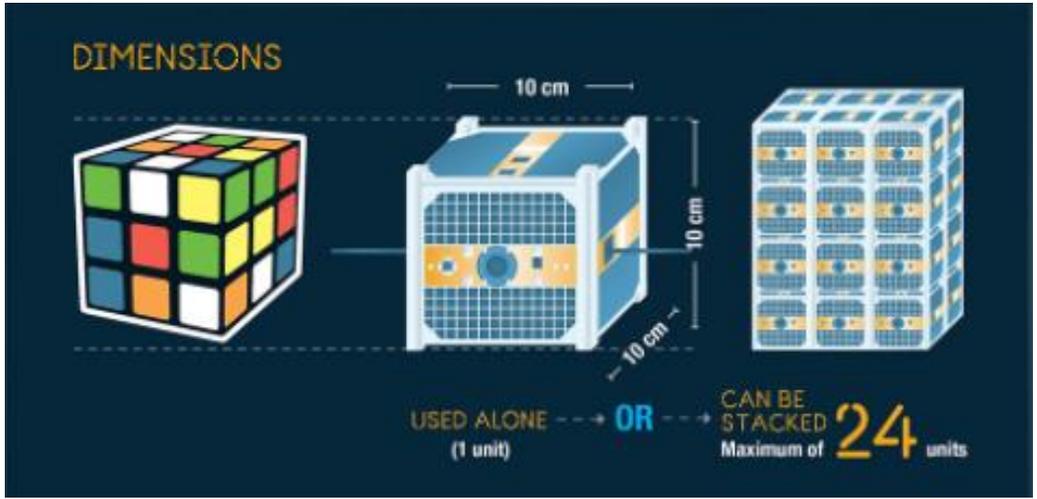
**BIRDS, EPS**

**by Hari Ram Shrestha, D2**

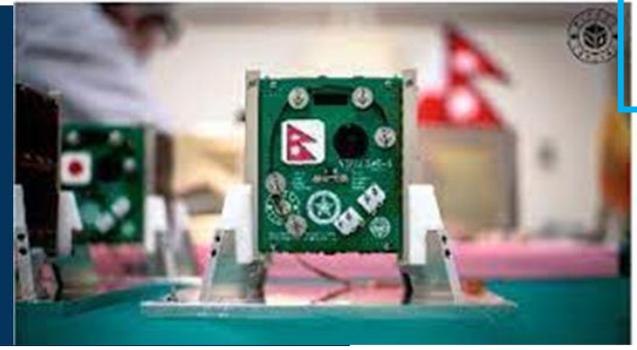
Email: [Shrestha.hari-ram852@mail.kyutech.jp](mailto:Shrestha.hari-ram852@mail.kyutech.jp)

**LaSEINE, Kyushu Institute of Technology, Japan**

# CubeSat & BIRDS Satellite project



FEATURE	SPECIFICATION
STANDARD	CUBESAT
DIMENSIONS	1U (113.5X100X100) MM
WEIGHT	1 KG (1.3KG)
HARNESS	BACKPLANE TYPE



BIRDS-3 (NepaliSat-1) satellite

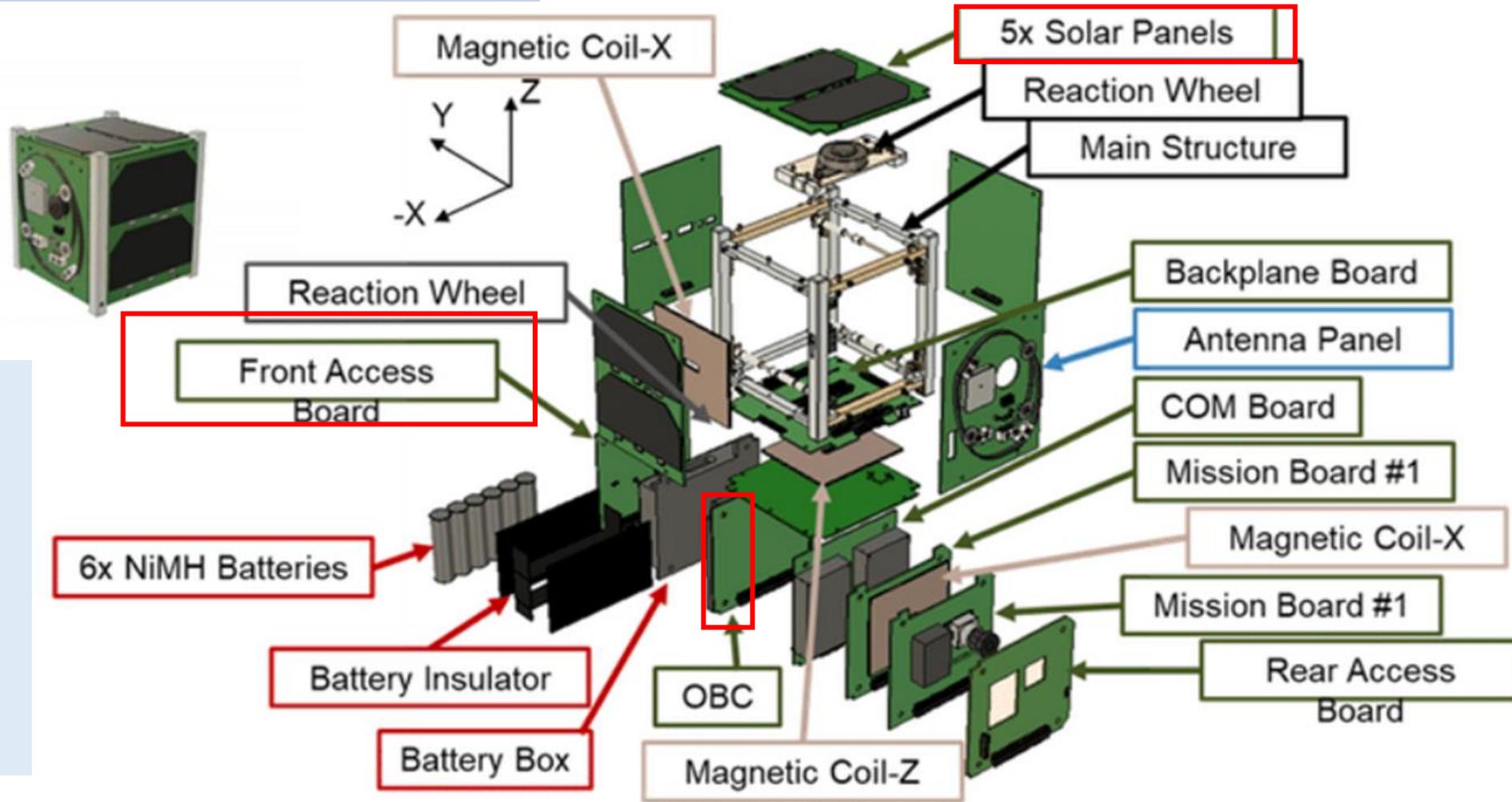


## BIRDS project satellites

- ❑ The Joint Global Multi-Nation Birds Satellite project. acronym as “Birds project.”



# CubeSat Overview and Subsystems



- ◆ Antenna and COM board
- ◆ Structure
- ◆ EPS (highlighted in red)
- ◆ OBC
- ◆ Payloads(CAM, ADCS,LoRa. etc)

**Electrical Power system (EPS) is a subsystem that has functions to provide uninterrupted power to all on-boards CubeSat electronics both in sunlight and in eclipse.**

## Functions

### 1. Power Generation

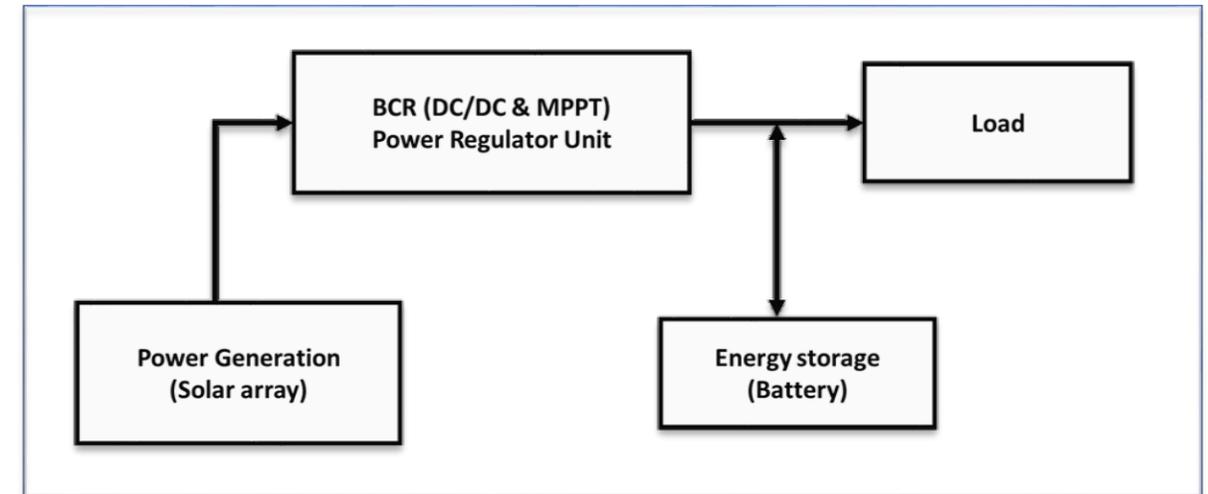
- Generate Power from 5 unit of Solar panels

### 2. Energy Storage

- Store the Excess power into 3S2P Ni-MH batteries

### 3. Power Management & Distribution

- Convert the Battery Voltage in to +5V and +3.3V and Unreg levels
- Supply Unregulated line, +5V and +3.3V to the Subsystems and OBC through ON/OFF controlled and overcurrent protected Lines

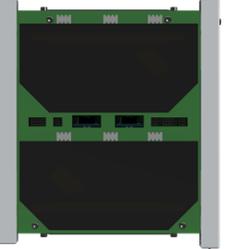
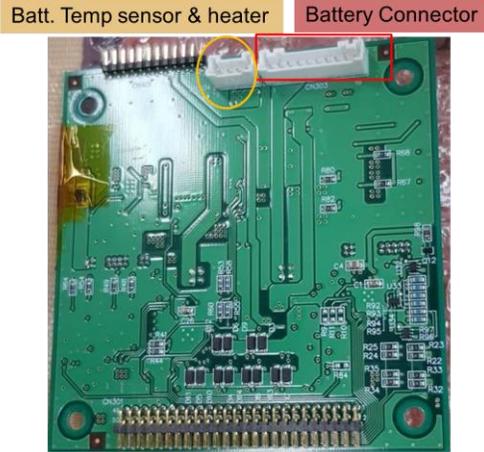
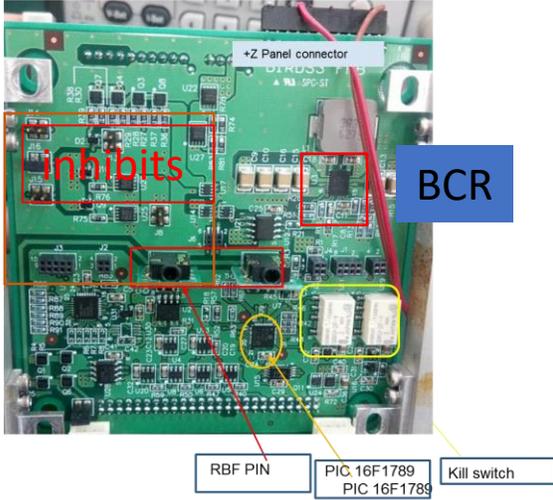


EPS block diagram

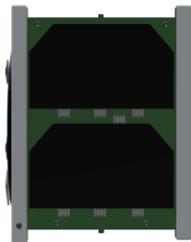
$$P_{LOAD} = (\eta_{BCR} * P_{GENmax}) \pm P_{STOR}$$

- Solar arrays are connected to Battery through Peak Power Tracking controlled regulator

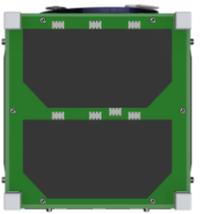
# EPS boards and components



+ Y



± X



± Z

RESET PIC at OBC board

TJ Solar Cell assembly 3G30A	
V max power per cell [V]	2.70 V
I max power per cell [A]	0.504
efficiency	0.293
area [m2]	0.003018

Batteries parameters	
Capacity per cell [mAh]	1900
Voltage avg. per cell [V]	1.2
weight per cell [g]	26.25
size per cell [mm]	14.10X 50.10
configuration	3S2P
Voltage total [V]	3.6
Total capacity [mAh]	3800
<b>Initial Energy capacity of battery pack[Wh]</b>	<b>13.68</b>



Eneloop NIMH battery

## A CubeSat's power budget defines

- power budget describes the balance between the generated power by the solar arrays and the consumed power by the loads on per orbit or per day.

Power profile,

Power consumption by satellite  $\leq$  Solar panel power generation



**DEFINE**

Test and analysis procedures:

- 1, MATLAB simulation power generation
- 2, Power consumption measurement (Each mission board and subsystem)
- 3, BIRDS-4 Flight data analysis
- 4, BIRDS-4 EM satellite ground test

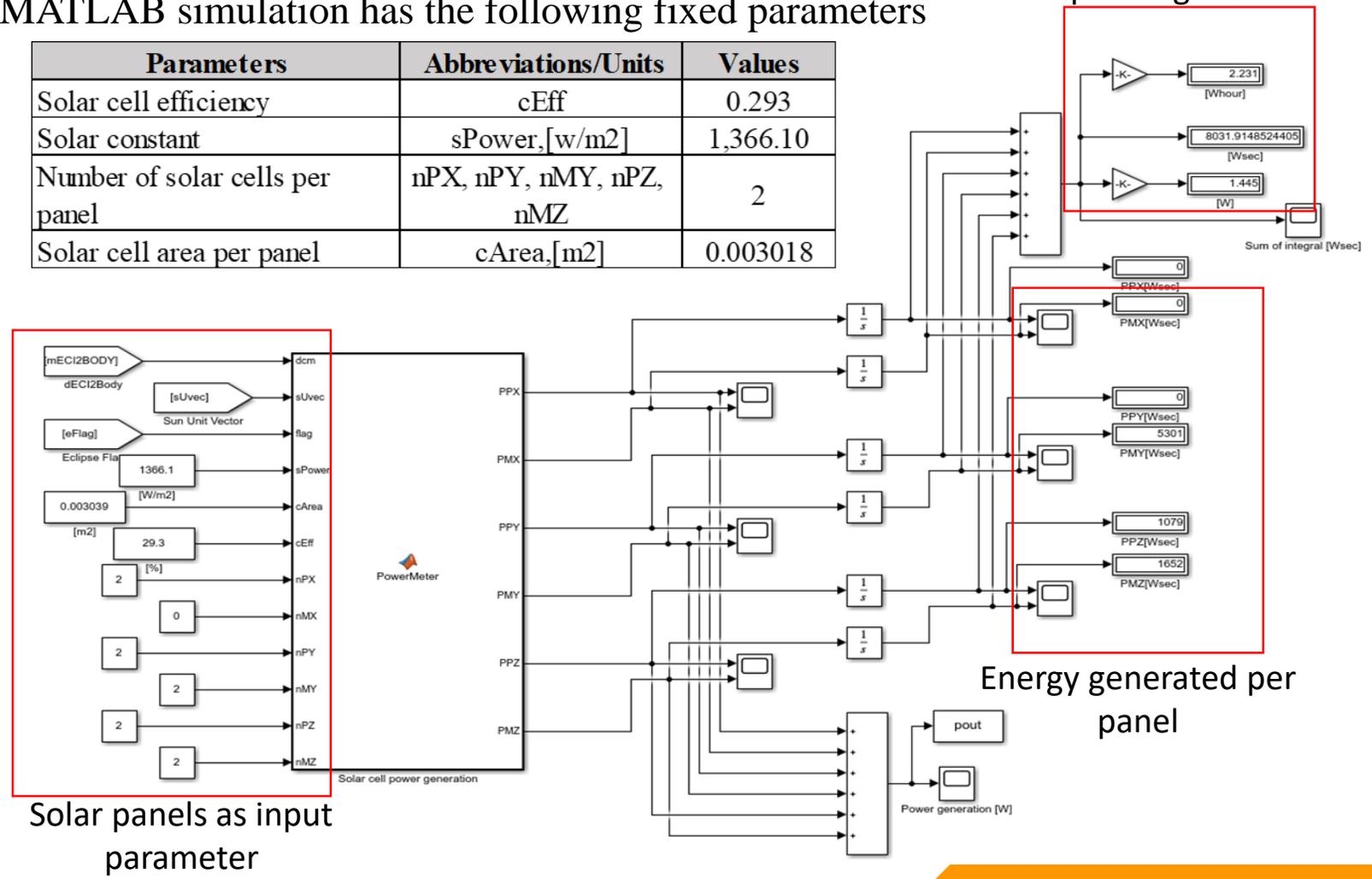


# Power generation simulation using MATLAB (1/2)

- There were three simulation conditions considered:
  - when all 5 panels are working
  - when 4 panels are working (no -X)
  - when 3 panels are working (no +Z and -X)
- Based on the conditions, MATLAB shall output total energy and power generated for a 90-minute orbit.
- Sunlit and eclipse time are considered in the simulation.

MATLAB simulation has the following fixed parameters

Parameters	Abbreviations/Units	Values
Solar cell efficiency	cEff	0.293
Solar constant	sPower,[w/m2]	1,366.10
Number of solar cells per panel	nPX, nPY, nMY, nPZ, nMZ	2
Solar cell area per panel	cArea,[m2]	0.003018



Solar panels as input parameter

Energy generated per panel

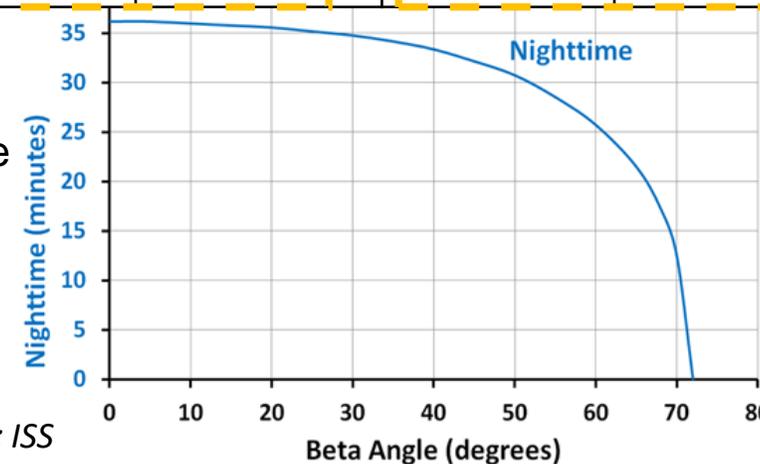


# Power generation simulation using MATLAB (2/2)

Parameters	Unit	Beta angle = 30 deg. Eclipse time = 35 min.			Beta angle = 73 deg. Eclipse time = 0 min.		
		5	4	3	5	4	3
Solar panels	-	5	4	3	5	4	3
Total Energy generated, <b>A</b> (MATLAB simulation)	mWh	2,173	1,875	1,419	3,447	2,980	2,252
Energy consumed by blocking diodes, <b>B</b> (Measured)	mWh	240			360		
BCR efficiency, <b>C</b> (Measured)	%	80			80		
Total Energy after BCR, <b>D</b> <b>D = (A-B)*C</b>	mWh	1,546	1,308	943	2,470	2,096	1,514

**NOTE:**

- Blocking diodes and buck-boost DC/DC converter (BCR) were characterized to obtain the measured values.



Reference: ISS



# BIRDS-4 Power Consumption (Measured)

- Power consumption per subsystem and per payload were measured
- The duration were subsystem and payload were ON is based on 90-minute orbit
- At nominal mode, BIRDS-4 satellites energy consumption is at 1,438 mWh**

- Mission boss, CPLD also used at Mission operation not at nominal operation

- Battery heater no need

COMPONENTS	OBC-EPS and FAB	COM UHF (RX)	COM UHF (TX-CW)	COM UHF (TX-Telemetry)	APRS-DP SF-WARD (RX)	APRS-DP SF-WARD (TX)	CAM	TMCR	PSC	HNT	ADCS (Stabilization)	ADCS (MCU and sensors ON)	ADCS (Pointing mode)	GPS	ADCS (Pointing Mode)	Mission Boss	Battery Heater	TOTAL ENERGY CONSUMPTION per Mission (mWh)
Maximum power allocated (mW)	428	144	280	4620	135	1400	300	50	16.5	500	0.75	188	1000	240	467	80	440	
Duration per orbit (h)	1.5	1	0.5	0.13	0.25	0.11	0.017	1.5	1.5	0.25	1	1.5	0.5	1.5	1.5	1.5	0.250	
Energy per Orbit (mWh)	642	144	140	600.6	33.75	154	5.1	75	24.75	150	0.75	282	500	360	700.5	120	110	
Nominal Mode	Command uplink and Beacon	ON	ON	ON	OFF	OFF	OFF	OFF	OFF	OFF	OFF	ON	OFF	OFF	OFF	ON	ON	1438
	Image and sensor data Downlink	ON	ON	ON	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	1527
	Camera Mission (mode 1 and 2)	ON	ON	ON	OFF	OFF	ON	OFF	OFF	OFF	OFF	ON	OFF	OFF	OFF	OFF	OFF	1213
	Camera Mission (mode 3 and 4)	ON	ON	ON	OFF	OFF	ON	OFF	OFF	OFF	OFF	OFF	ON	ON	OFF	OFF	OFF	1791
	ADCS Initail Mode	ON	ON	ON	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	ON	ON	OFF	OFF	1987
	ADCS Determination	ON	ON	ON	OFF	OFF	OFF	OFF	OFF	OFF	OFF	ON	OFF	ON	OFF	OFF	OFF	1568
	ADCS Stabilization	ON	ON	ON	OFF	OFF	OFF	OFF	OFF	OFF	ON	ON	OFF	ON	OFF	OFF	OFF	1569
	APRS-DP and SF-WARD Mission	ON	ON	ON	OFF	ON	ON	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	ON	OFF	1234
	HNT Mission	ON	OFF	OFF	OFF	OFF	OFF	OFF	OFF	ON	OFF	OFF	OFF	OFF	OFF	ON	OFF	912
	PSC Mission	ON	ON	ON	OFF	OFF	OFF	OFF	ON	OFF	OFF	OFF	OFF	OFF	OFF	ON	OFF	1071
	TMCR Mission	ON	ON	ON	OFF	OFF	OFF	ON	OFF	OFF	OFF	OFF	OFF	ON	OFF	ON	OFF	1481
	ICU Mission	ON	ON	ON	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	926
	Deployment(30 mins)	ON	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	ON	752



# Nominal consumption of other satellites

COMPONENTS	OBC-EPS, FAB + COM UHF (RX)	OBC-EPS, FAB + COM UHF(TX-CW)	400MHz LoRa Board	920MHz LoRa Board	TOTAL ENERGY CONSUMPTION per Mission (mWh)
Maximum power allocated (mW)	604.8	987	805	616	
Duration per orbit (h)	1.115	0.418	0.167	0.167	
Energy per Orbit (mWh)	674.35	412.57	134.44	102.87	
Command uplink and Beacon	<b>ON</b>	<b>ON</b>	<b>OFF</b>	<b>OFF</b>	<b>1087</b>

MO-1 satellite

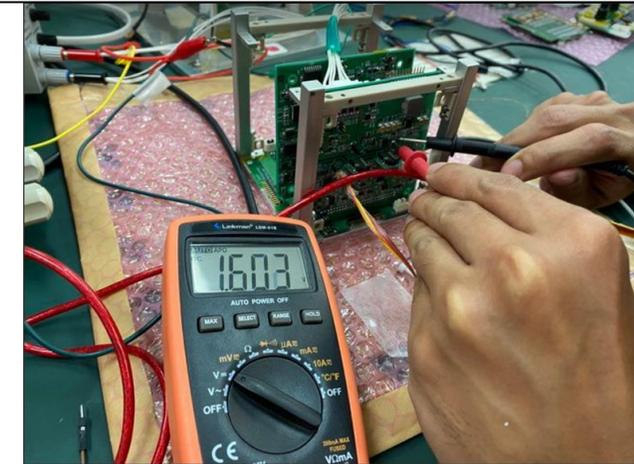
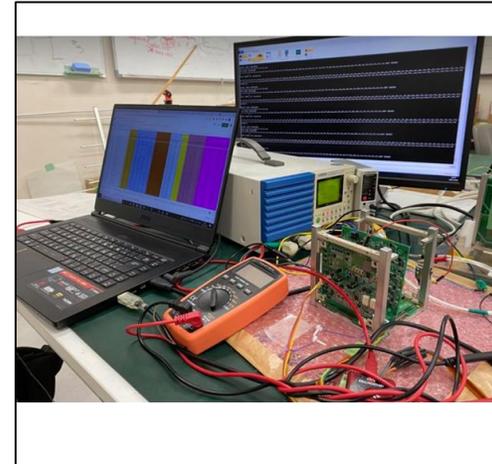
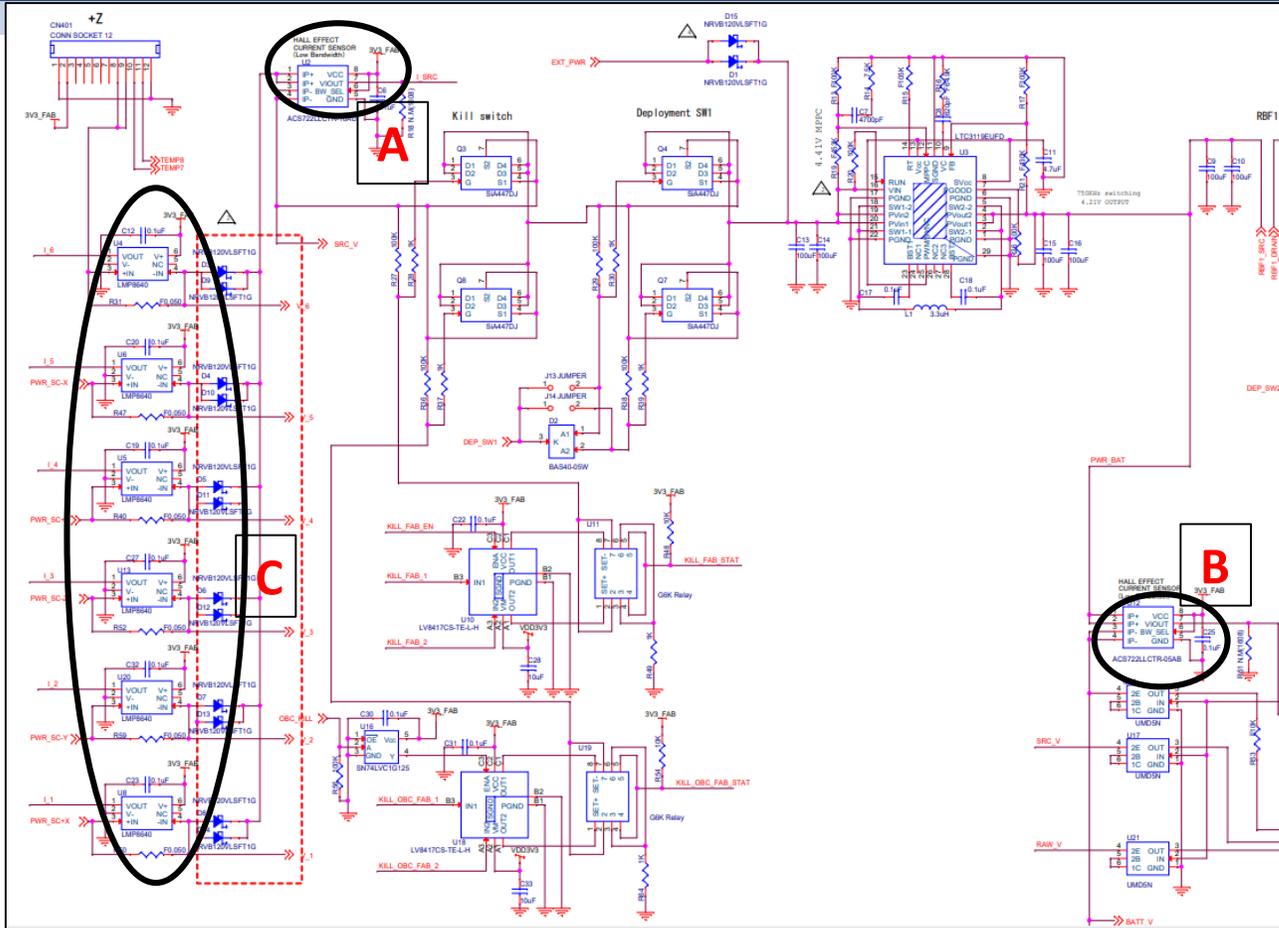
Power Consumption (mWh) and Operational Status per Orbit	COMPONENTS	OBC-EPS-FAB-COM UHF (RX)	OBC-EPS-FAB-COM UHF (TX-CW)	OBC-EPS and FAB	COM UHF (TX-Telemetry)	APRS-DP SF-WARD (RX)	APRS-DP SF-WARD (TX)	MultiSpec CAM Mission	ICU Mission (With RGB Cam)	ADCS (Determination MCU and sensors ON)	Mission Boss & CPLD	(Antenna Deployment) Burner Circuit	TOTAL ENERGY CONSUMPTION per Mission (mWh)
	Maximum power allocated (mW)	604.8	987	410	4054.6	280	1710	3200	1321.1	480	123.5	12600 (one time)	
	Duration per orbit/Duty cycle (h)	1.115	0.418	1.53	0.117	0.25	0.11	0.1	0.1	0.25	0.25	2.78x10 <sup>-4</sup>	
	Energy per Orbit (mWh)	674.35	412.57	627.3	474.3882	70	188.1	320	132.1	120.0	30.875	3.5	
	Command Uplink and Beacon	<b>ON</b>	<b>ON</b>	<b>OFF</b>	<b>OFF</b>	<b>OFF</b>	<b>OFF</b>	<b>OFF</b>	<b>OFF</b>	<b>OFF</b>	<b>OFF</b>	<b>OFF</b>	
Image and Sensor Data Downlink	<b>ON</b>	<b>ON</b>	<b>OFF</b>	<b>ON</b>	<b>OFF</b>	<b>OFF</b>	<b>OFF</b>	<b>OFF</b>	<b>OFF</b>	<b>ON</b>	<b>OFF</b>	<b>1592.18</b>	

BIRDS-5





# Current sensors calibration



- Measurements were taken on the source current sensor (A), battery current sensor (B), and individual solar panel source current sensors (C) with under different temperature conditions: +25 degC, +60 degC, -10 degC
- Based on the measurements, each sensor's HK data formula were updated.

BIRDS-4 FAB schematic

Calibrated equation are,

$$I_{bat}, Y = -3686.1x + 5980.2$$

$$I_{src}, Y = 3905.2x - 1268.3$$

$$I_{raw} = 3986.3x - 1429.9$$



# Power generation (Tsuru on-orbit data)

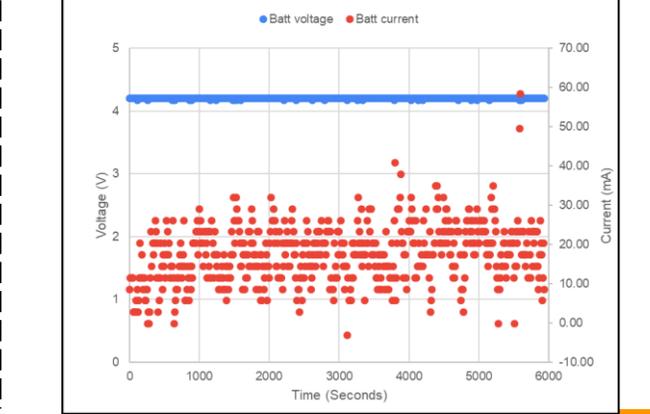
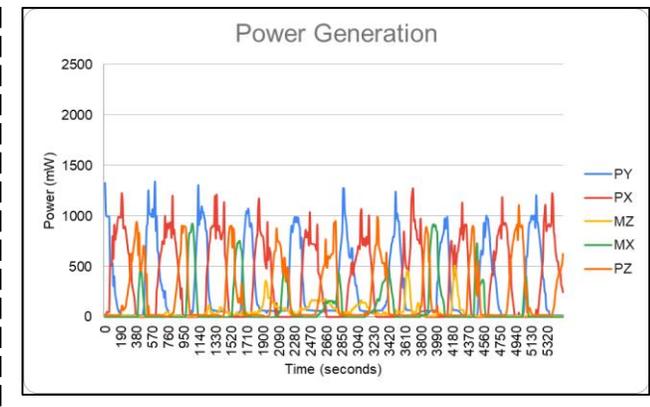
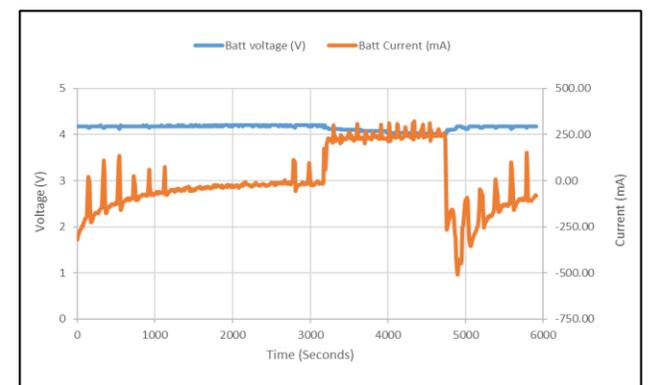
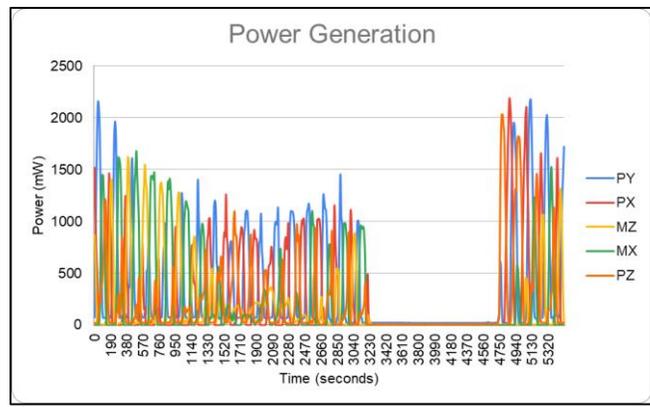
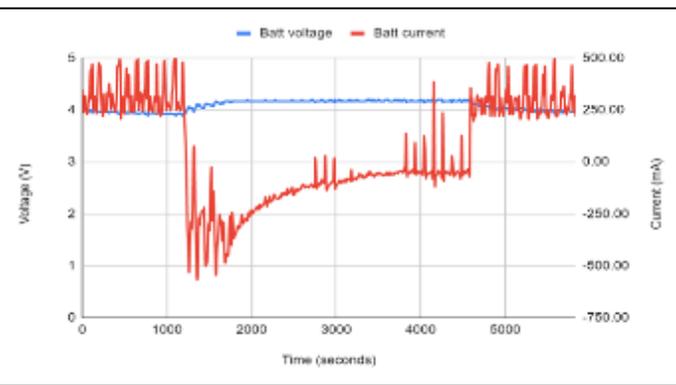
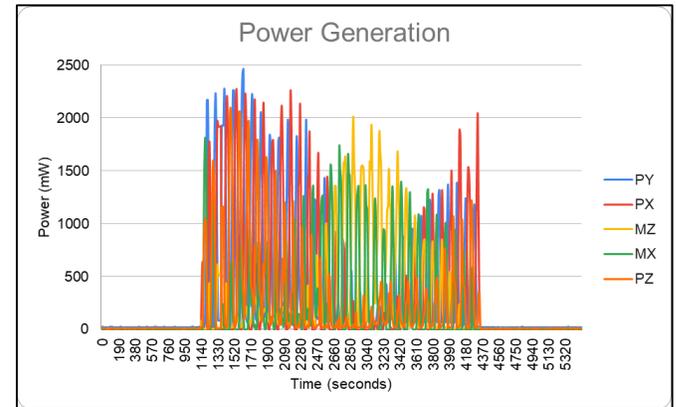
Date	June 1, 2021	July 9, 2021	July 17, 2021
Beta angle	0 deg	50 deg	70 deg
Power Generated	1,790 mWh	1,658 mWh	1,560 mWh

## Conditions

- 5 panels working
- GPS is OFF
- Battery heater is OFF

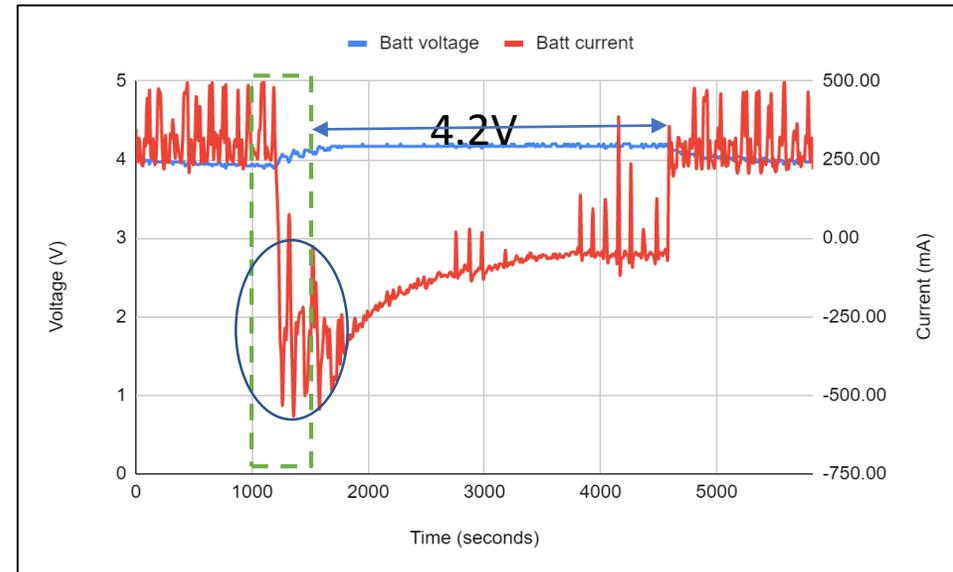
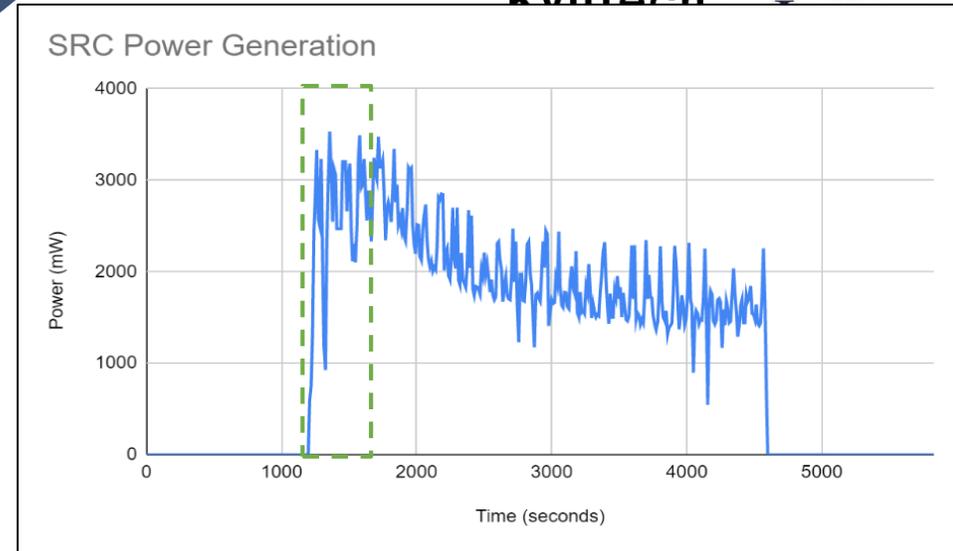
## Observation

- Generated power is highest at 0 deg beta angle



# Available power to the load at 0 deg Beta angle (Tsuru on-orbit data)

- At 0 deg Beta angle, sunlit period is at 3,380 seconds (~56.3333 min.)
- It takes around 600 seconds for the battery to charge and reach 4.2 V when the satellite transitions from eclipse to sunlit.
- The average power generated during the 600 seconds period is



Parameters	Unit	Beta angle = 0 deg. Eclipse time = 36 min.		
		5	4	3
Solar panels	-	5	4	3
Generated power	mW	2,670	2,136	1,602
Generated energy, <b>A</b>	mWh	2,507	2,005	1,504
Energy consumed by blocking diodes, <b>B</b>	mWh	240	192	144
BCR efficiency, <b>C</b>	%	80		
Energy loss at battery, <b>D</b>	mWh	210		
Available Energy to the load, <b>E</b> <b>E = [(A - B)*C] - D</b>	mWh	1,604	1,240	878

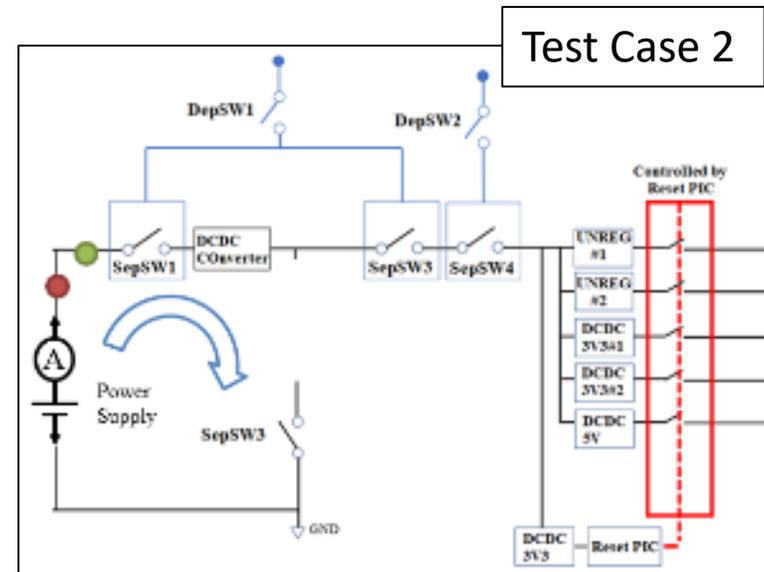
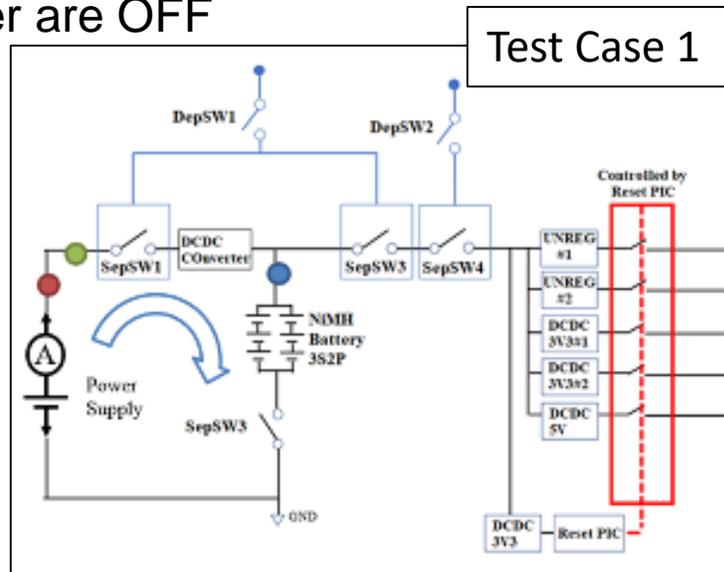


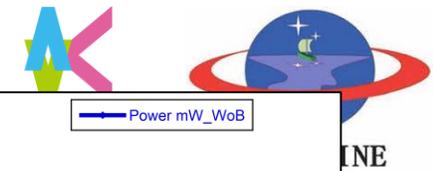
# BIRDS-4 EM satellite test (1/2)

- EM satellite was used to verify the power consumption.
- Test cases
  - With fully-charged battery
  - Without battery
- Test setup:
  - antenna deployed
  - all internal boards are connected to the backplane
  - no solar panels
  - regulated power (4.2 V) supplied to the satellite through FAB J5 connector for case 1 and solar panel connector for case 2
  - GPS and battery heater are OFF



Test setup (Case 2)

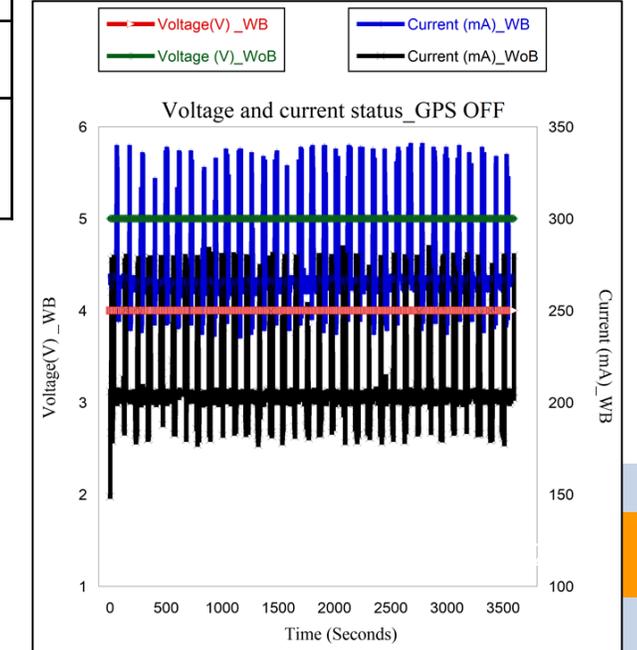
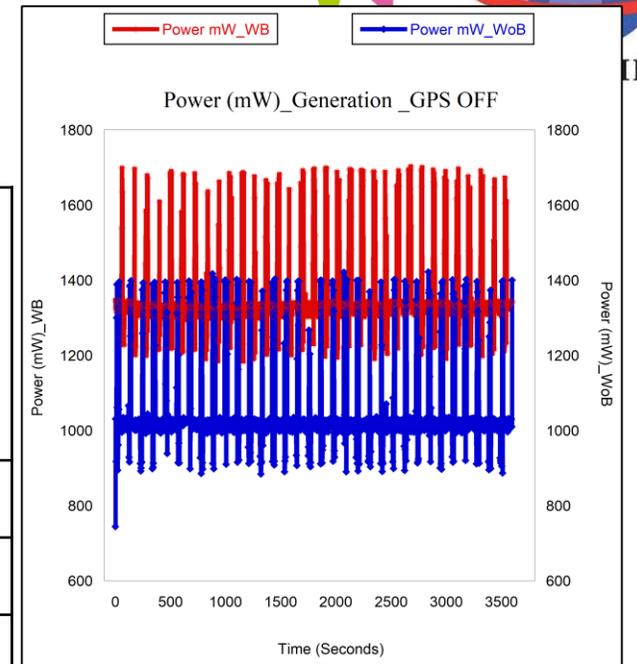




# BIRDS-4 EM satellite test result (2/2)

Parameters	Unit	Power Source With Battery Connection (WB) Case-1	Power Source With - out Battery Connection (WoB) Case-2
Generated energy, <b>A</b>	mWh	2039	1578
Blocking diodes loss, <b>B</b>	mWh	360	
BCR efficiency, <b>C</b>	%	80	
Energy loss at battery, <b>D</b>	mWh	210	-
Available Energy to the load, <b>E</b> <b>E = [(A - B)*C] - D</b>	mWh	1133	974

NOTE: - Blocking diode loss (**B**), BCR efficiency (**C**), and energy loss in battery (**D**) are measured and same in page 7



- For on-orbit at worst case, the available energy is 1604 mWh (at 5 solar panels)
- And, according to ground test results the available energy 1133 mWh

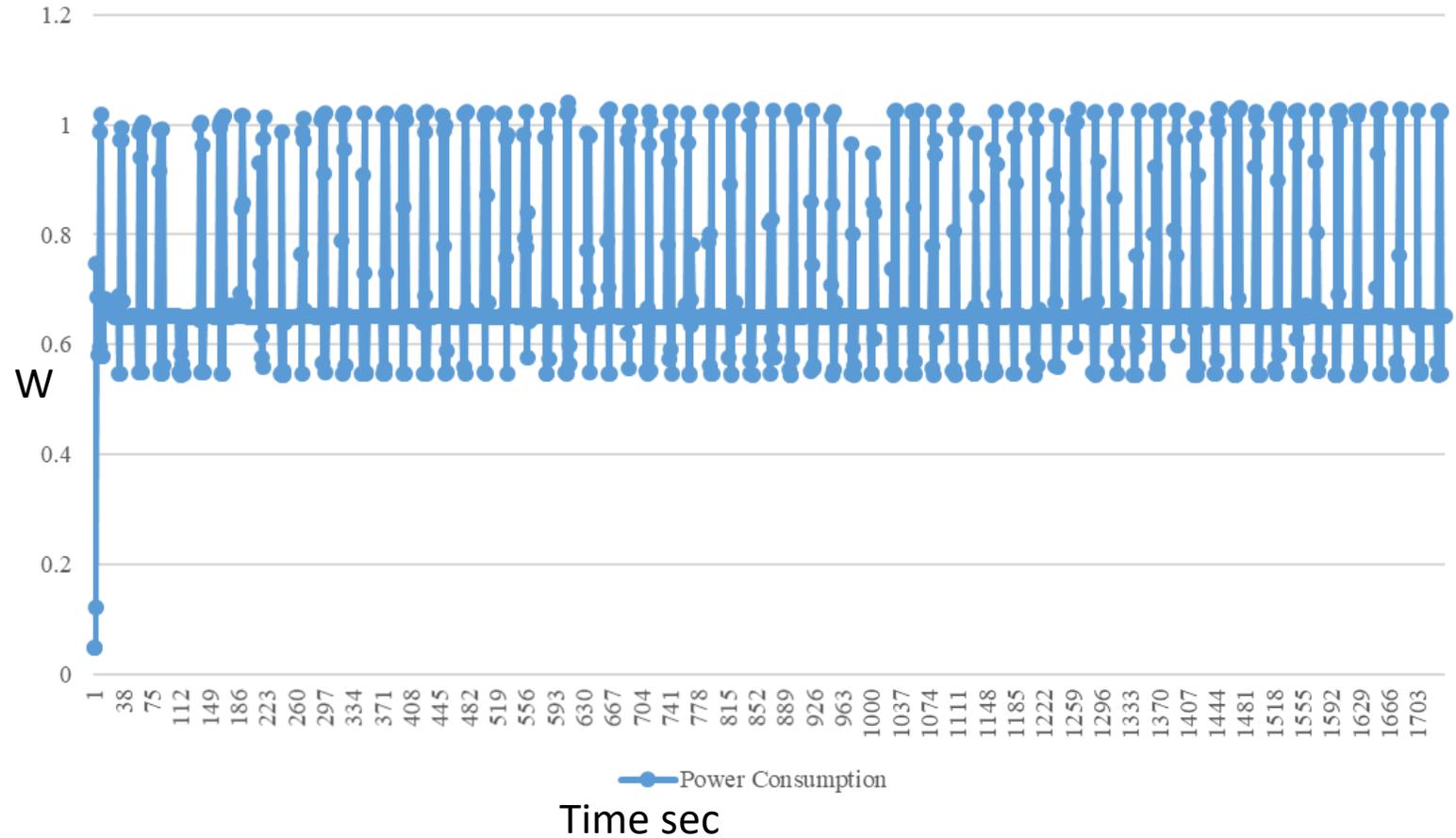
The results of the on-orbit and ground tests are not exactly equivalent because,

- ✓ During test battery was fully charged and receiving in constant power from power source

# Nominal power consumption

- ❑ High Sampling Data from BIRDS-5 FM satellite (30 Minutes) Nominal power consumption = 650mW.
- ❑ Hence total energy consumption = 700 mW x 1.5 h (Orbital period) = 1050 mWh.

Power Consumption for SAT2



- **Focus on power budget reliability based on flight data** rather than simulation. The estimated power generation in one orbit is *2500mWh* in one orbit and the available power to the load is *1600mWh* for the case of 5 solar panels working
- Estimate the Power Generation from the satellite in **the worst-case** (Low Beta)>>please follow this rule.
- The nominal power consumption of the satellite per orbit should be around 1000mWh or less, so that the satellite can continue to function even **if one solar panel fails**
- Due to the general flight experiences of the BIRDS-3 and BIRS-4 satellites, there is **no need to use a battery heater on the satellite**.(we can save the energy).
- Power generation can vary depending on the **satellite's TLE (high or low beta angle)**, initial orientation, rotation speed, and other parameters.

## EPS functionality tests

### Safety review

Inhibit test (overcharge, over discharge and external short)

>> Deployment switch screening and Inhibit test

>> Battery screening and cell matching after doing environmental test (Vacuum, vibration)

>> Battery Lot sampling test at high temperature

Functional test

MPPC and BCR efficiency test

Diode (reverse) test

Battery recover test

Housekeeping data analysis (sensor calibration)

Solar cells attachment and its characterization

Each component power consumption (nominal and rush current) test

Over current protection and sensitivity test

FAB PIC and RESET PIC communication with Main PIC and COM PIC

# Acknowledgements



- ❑ Prof. Mengu Cho

- ❑ BIRDS members

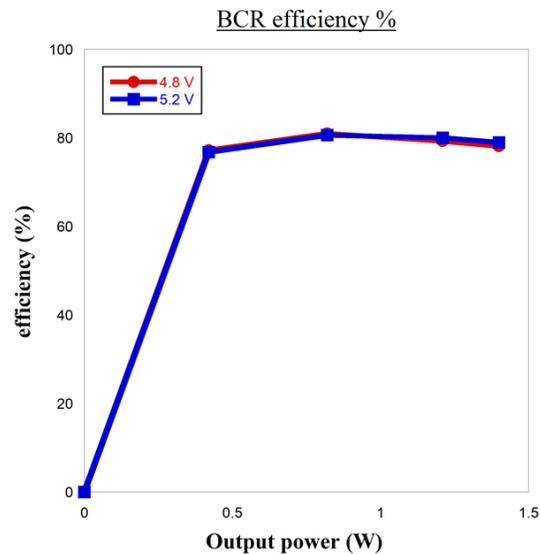
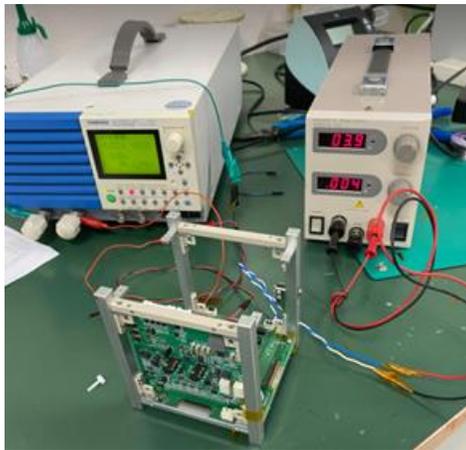
Test and Data Analysis :Hari, IZ , Adolfo ,Marloun

Thank you



□ Appendix

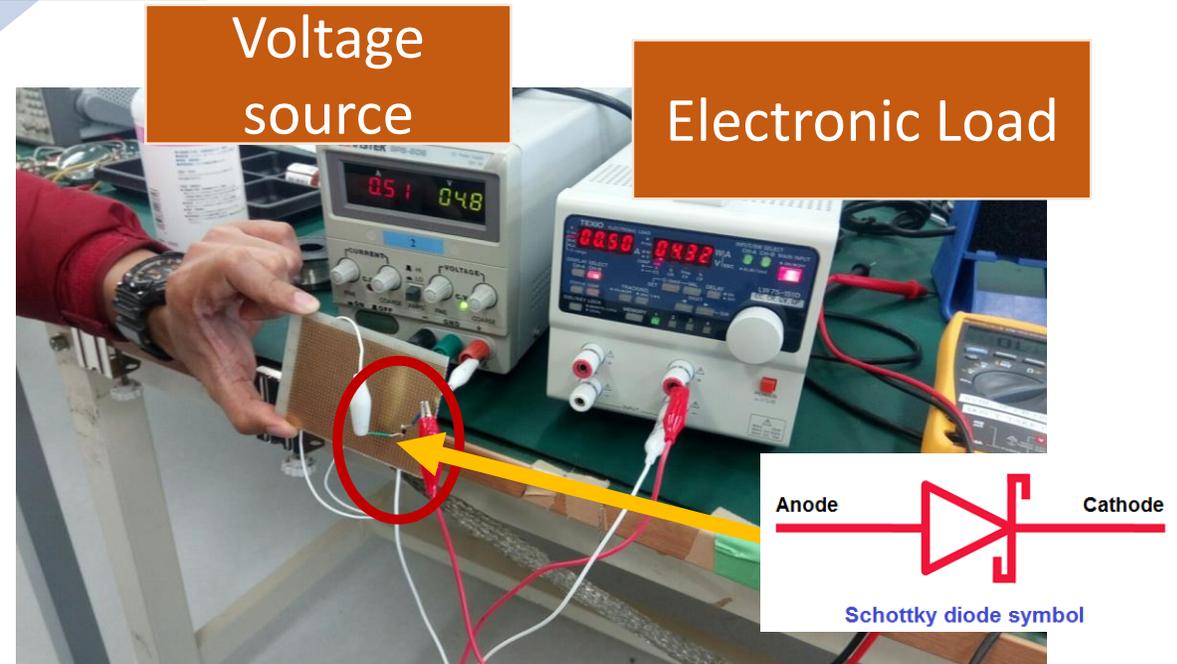
# Blocking Diode and BCR Characterization



- Efficiency % = (Output power (w)/ Input power (W))X100%

Test condition,

1. At 4.80 V Input constant voltage
2. At 5.20 Input voltage constant voltage



Test appearance

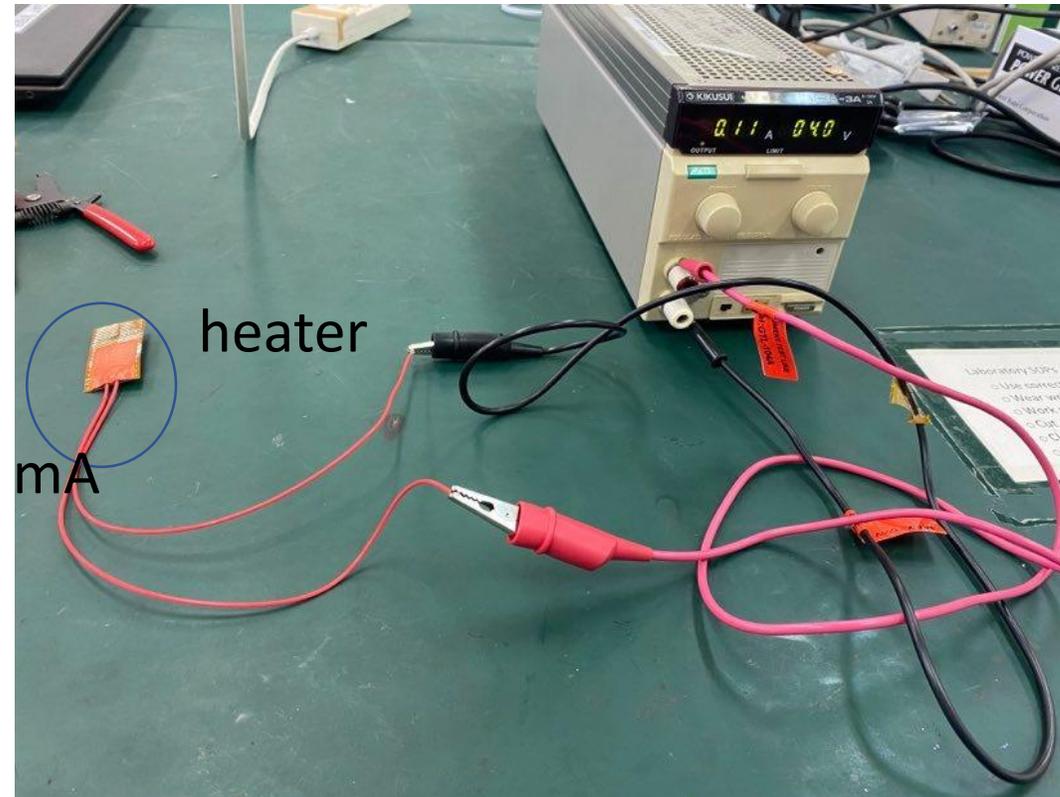
- Voltage source =4.8 V
- Consume current by electronic load by= 0.5 A
- Voltage drop=0.48 V
- Power loss= 240mW

# Battery heater calculation

Supply voltage = 4.0 V to 4.2 V  
Heater resistance = 40  $\Omega$

$$I = V/R$$

Current consuming = 110 mA to 130 mA





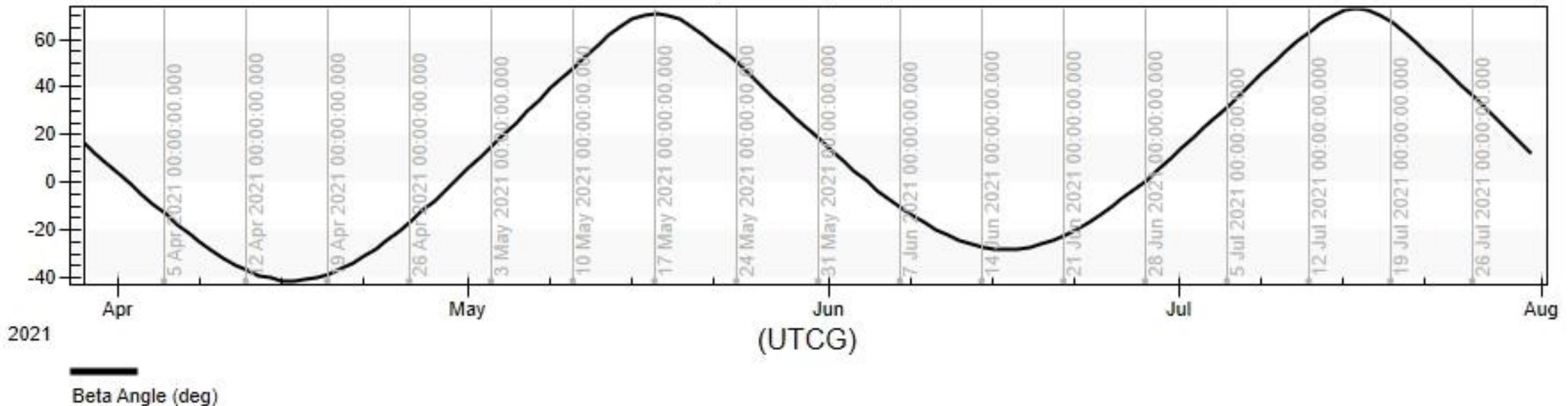
# Beta Angle Prediction (March to July 2021)

Parameters:

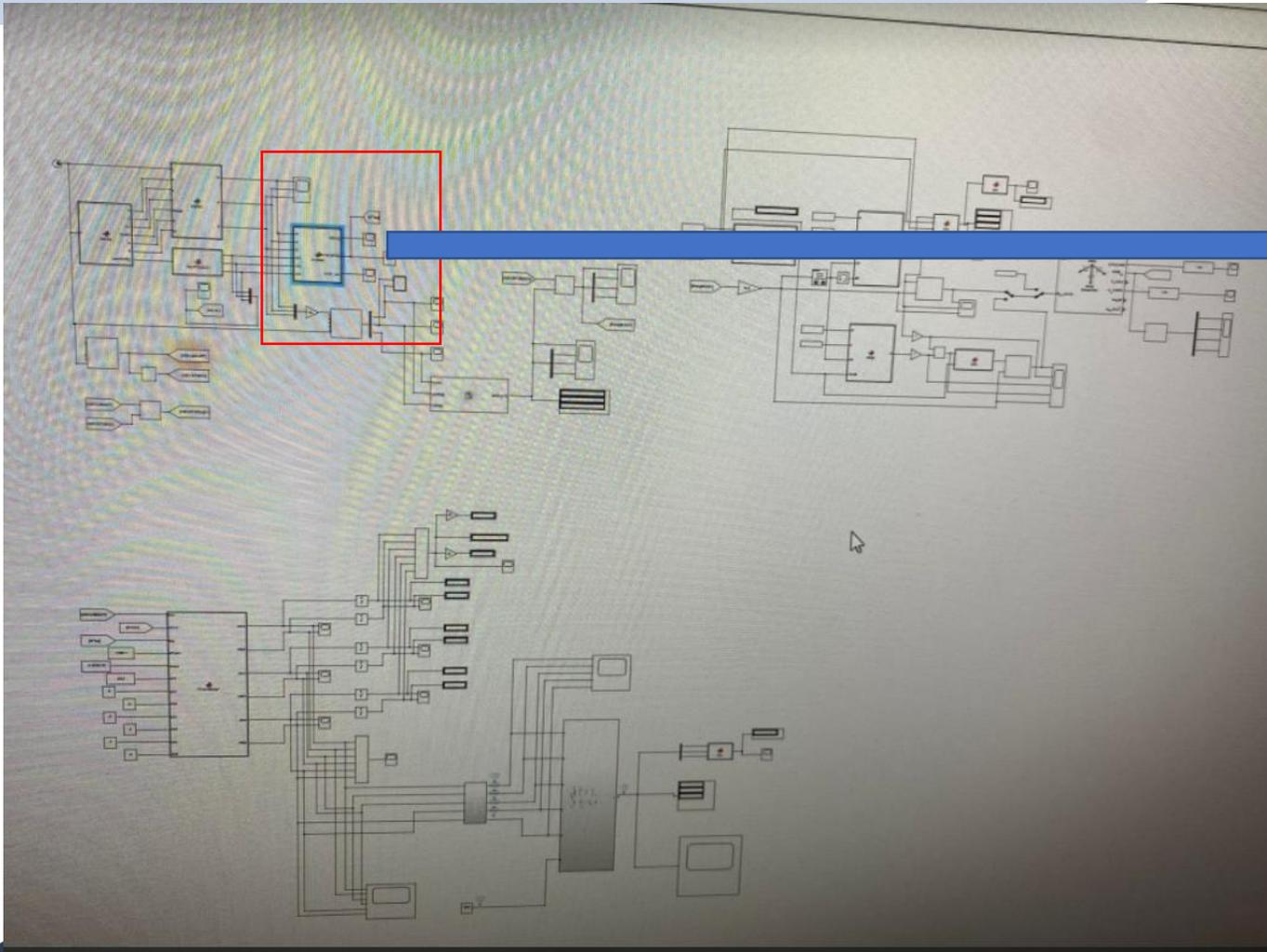
Elevation = 416.86 km

Inclination = 51.6444 deg

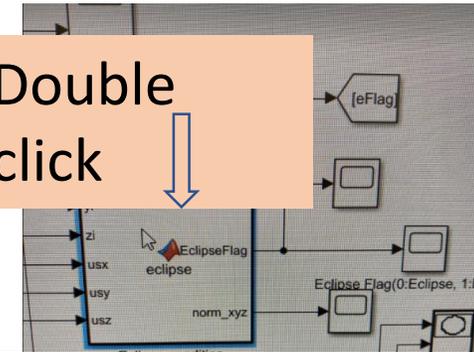
**BIRDS4 Beta Angle Simulation**  
(March to July 2021)



# Simulation task



Double  
click



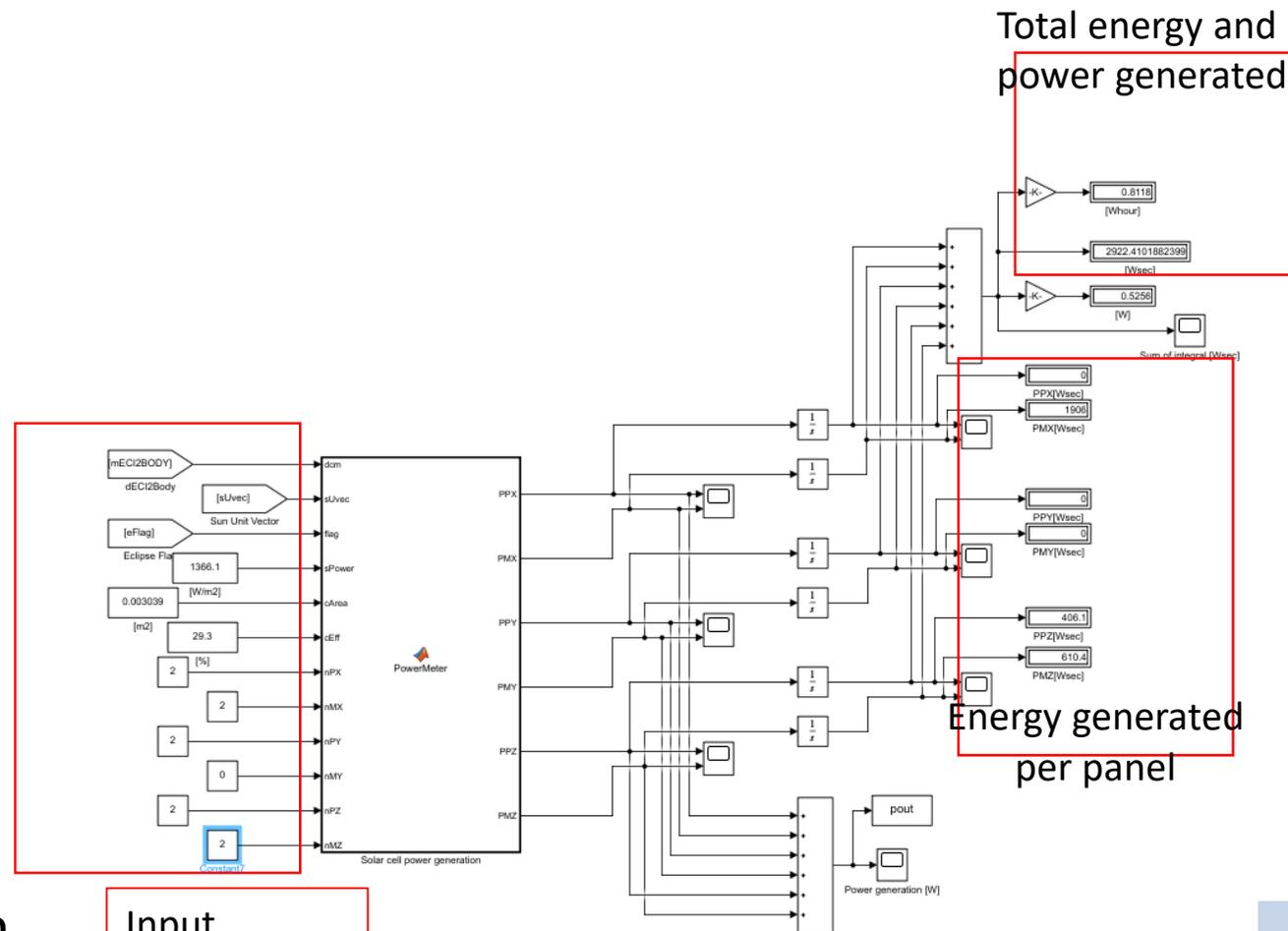
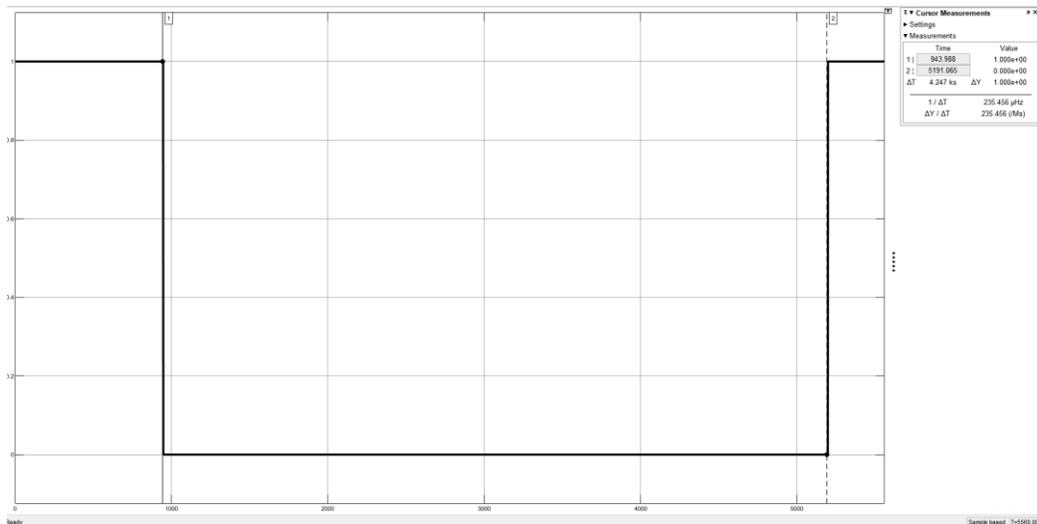
```
1 function [dpDeg,EclipseFlag, norm_xyz] = eclipse(xi,yi,zi,usx,usy,usz)
2 %% Constants for calculation
3 rEarth = 6356.7523; %Polar Earth radius by WGS84 [km]
4 deg2rad = 3.141592/180.0;
5 rad2deg = 180.0/3.141592;
6
7 %% Unit vector for the position of satellite in ECI
8 norm_xyz = sqrt(xi*xi+yi*yi+zi*zi);
9 ux = xi/norm_xyz;
10 uy = yi/norm_xyz;
11 uz = zi/norm_xyz;
12
13 %% Angle condition for the eclipse
14 eclipseAngle = acos(rEarth/norm_xyz);
15 eclipseAngleRad = deg2rad*90.0 + eclipseAngle;
16
17 %% Check the ecipse condition
18 dp = ux*usx + uy*usy + uz*usz;
19 dpAngRad = acos(dp);
20
21 if dpAngRad > eclipseAngleRad
22     a = 0;
23 else
24     a = 1;
25 end
26
27 dpDeg = dpAngRad*rad2deg;
28 EclipseFlag = a;
29
```



# Power generation simulation using MATLAB

```
%% Angle condition for the eclipse
eclipseAngle = acos(rEarth/norm_xyz);
eclipseAngleRad = deg2rad*30.0 + eclipseAngle;
```

With 5 solar panels working  
(+X, -X, +Y, +Z, -Z)



Total energy and power generated

Energy generated per panel

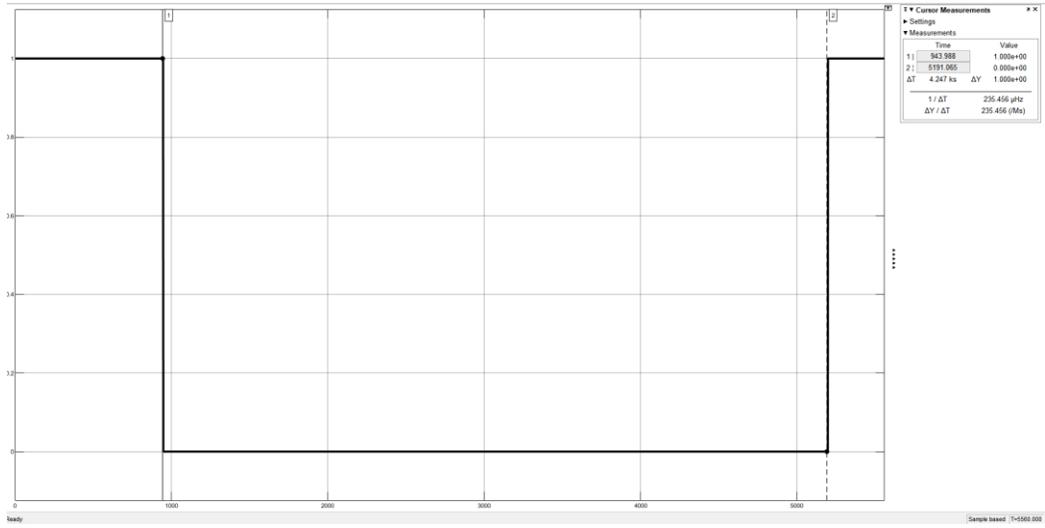
Eclipse time is 72 min

Input parameters to the simulation

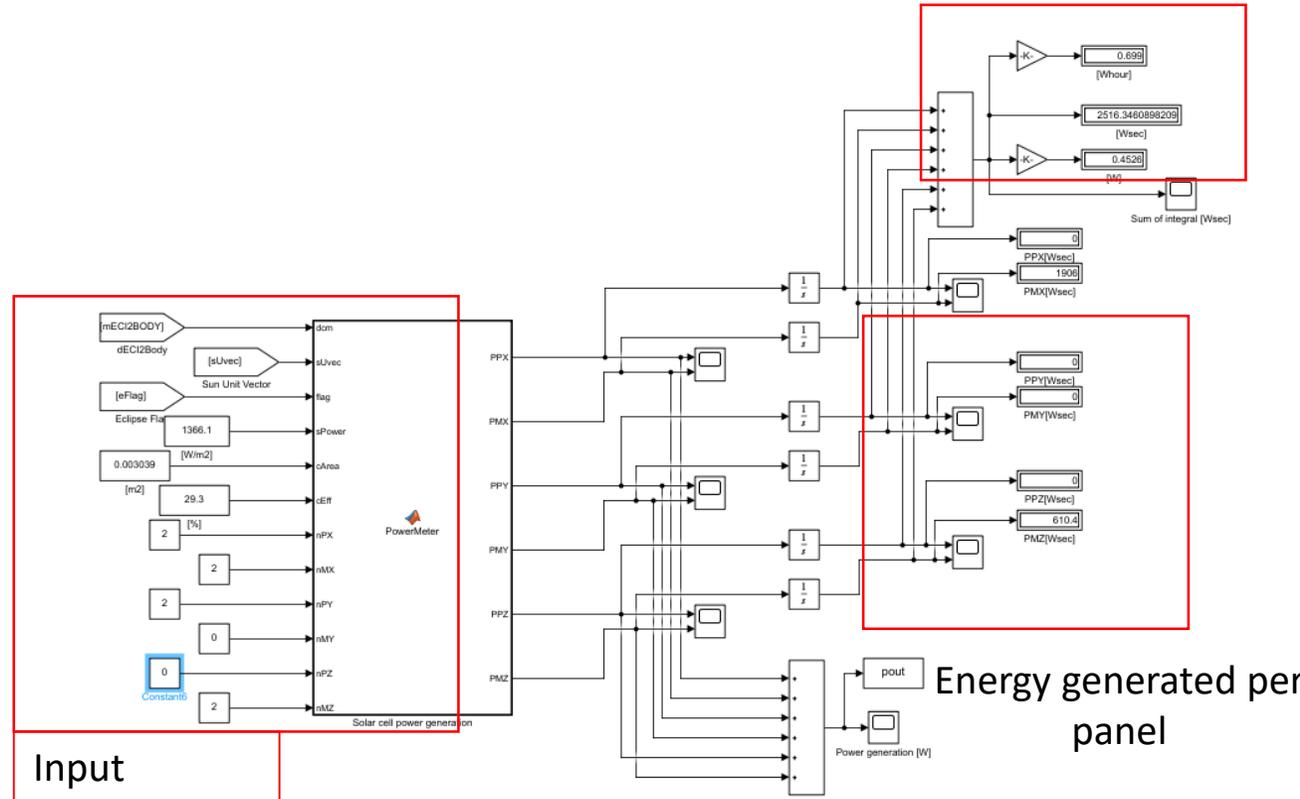
# Power generation simulation using MATLAB

```
%% Angle condition for the eclipse
eclipseAngle = acos(rEarth/norm xyz);
eclipseAngleRad = deg2rad*30.0 + eclipseAngle;
```

With 4 solar panels working  
(+X, -X, +Y, -Z)



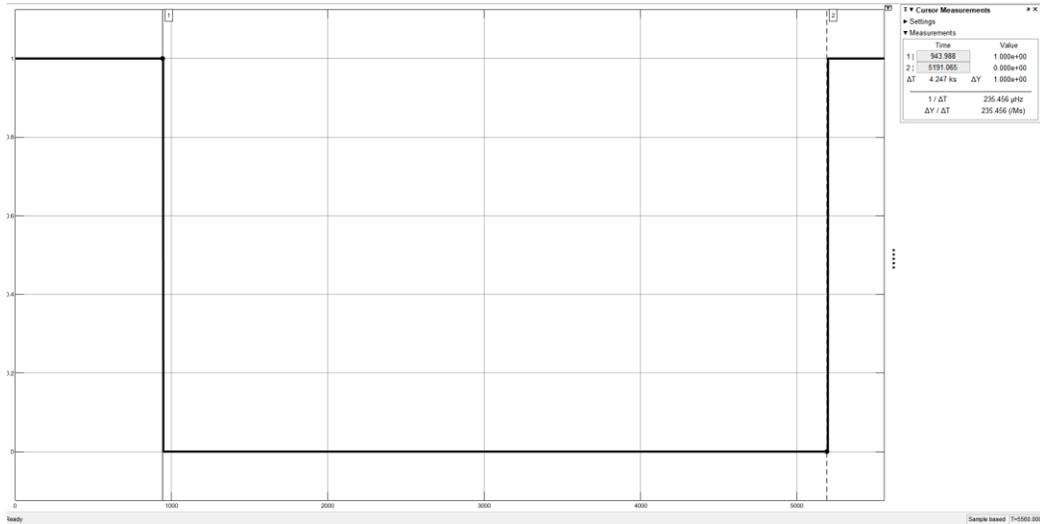
Total energy and power generated



# Power generation simulation using MATLAB

```
%% Angle condition for the eclipse
eclipseAngle = acos(rEarth/norm xyz);
eclipseAngleRad = deg2rad*30.0 + eclipseAngle;
```

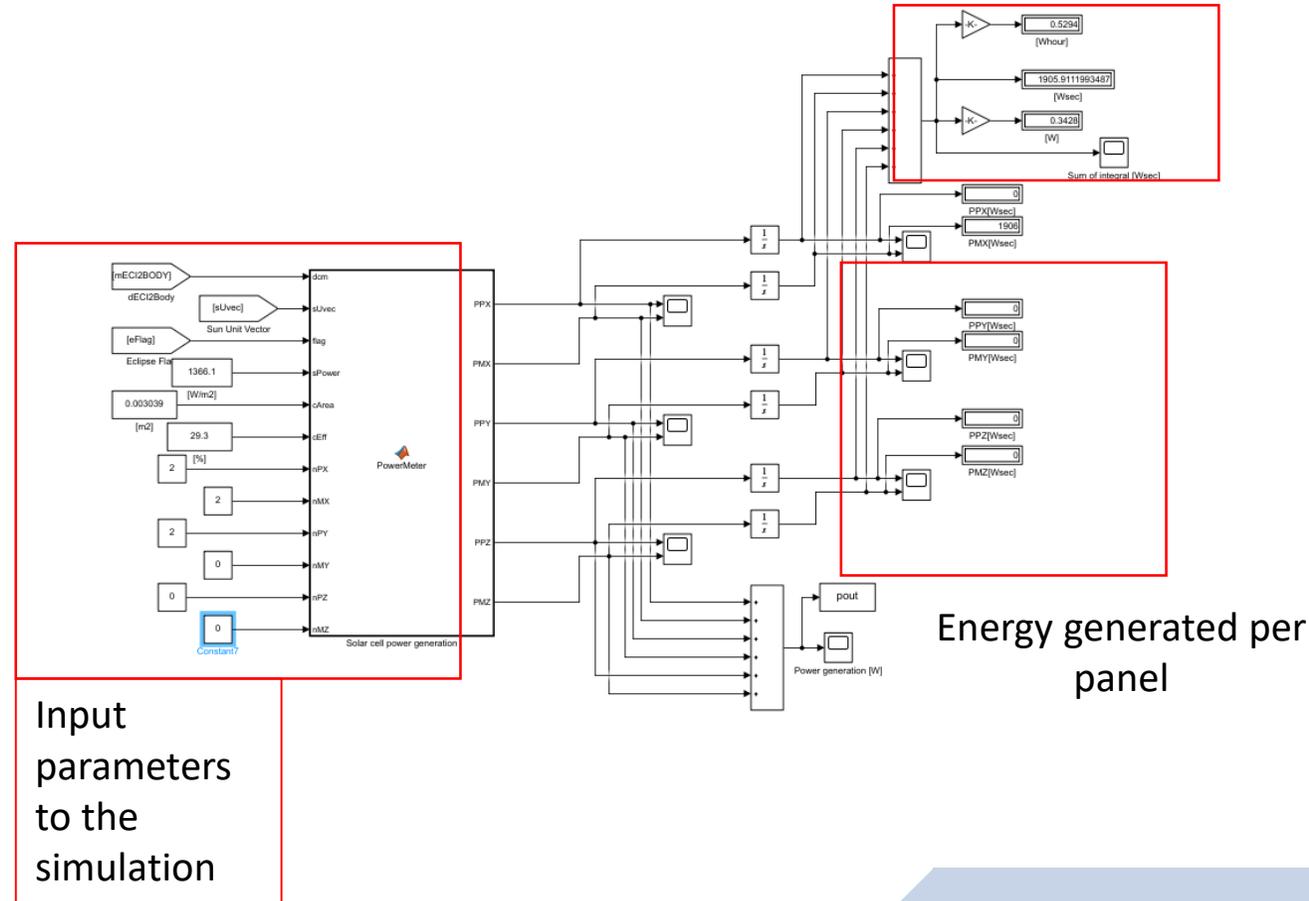
With 3 solar panels working (+X, -X, +Y)



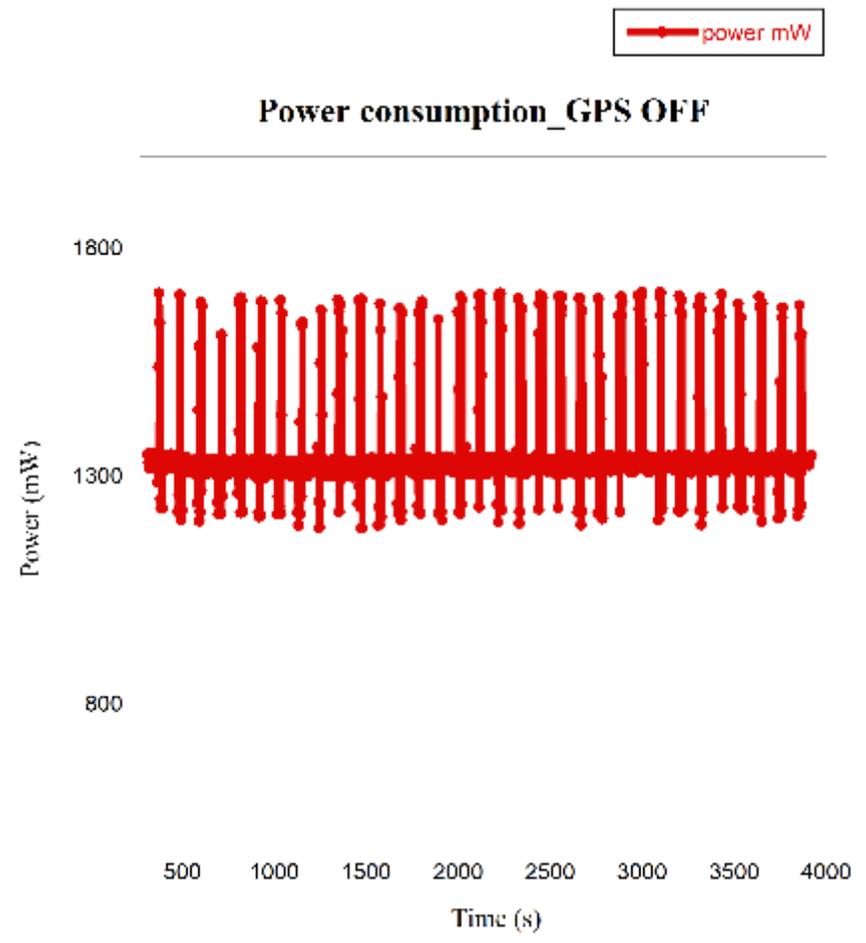
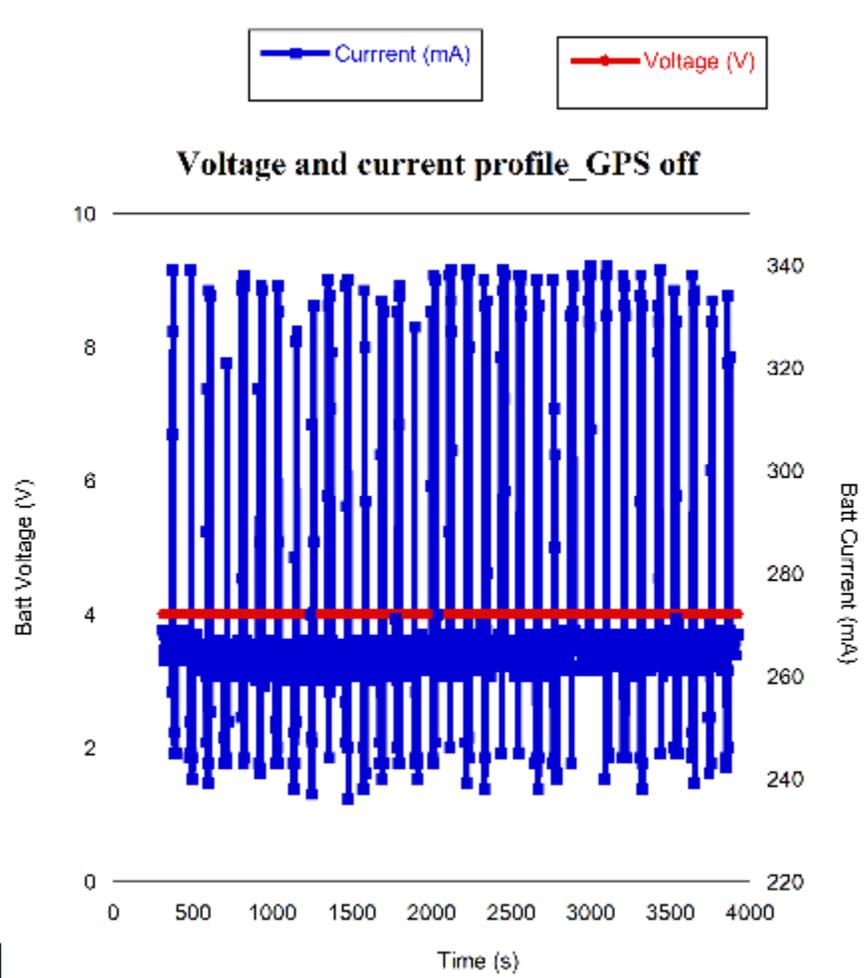
**Kyutech**  
Kyushu Institute of Technology



Total energy and power generated

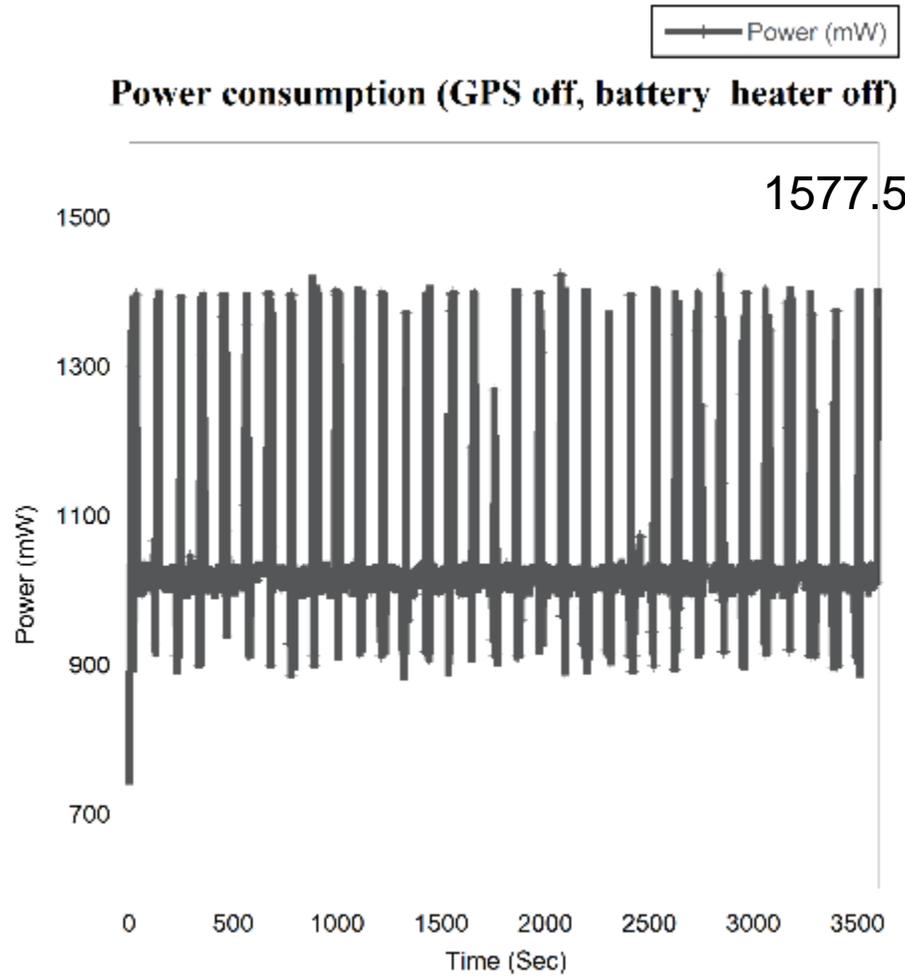


# Test with battery connected (GPS OFF, heater OFF)

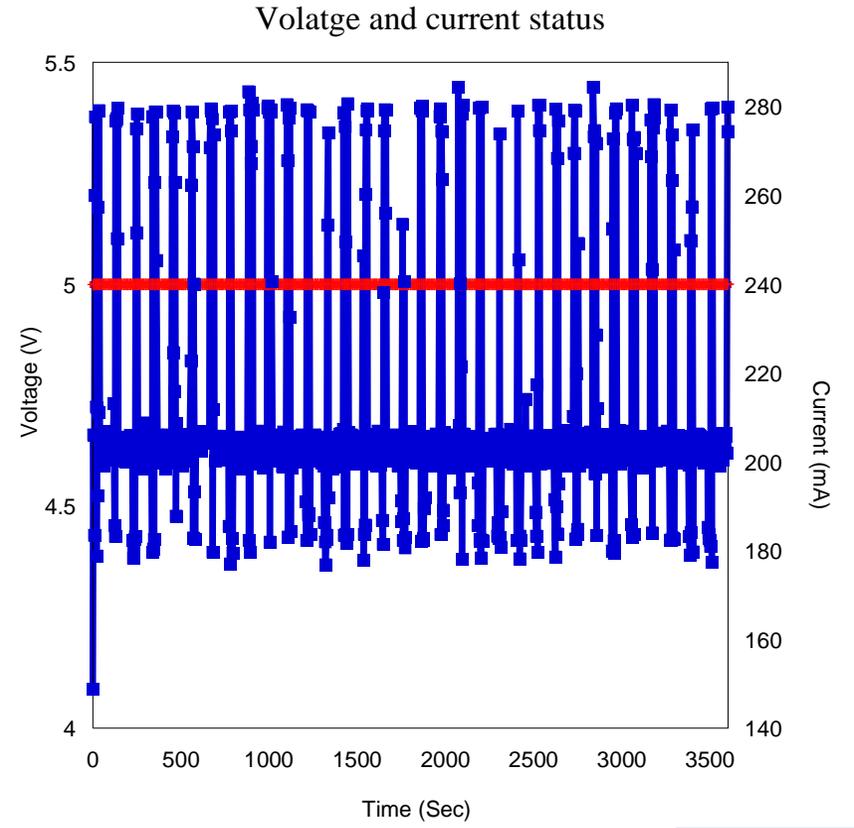


# Test without battery connected (GPS OFF, heater OFF)

Power consumption (GPS off, battery heater off)

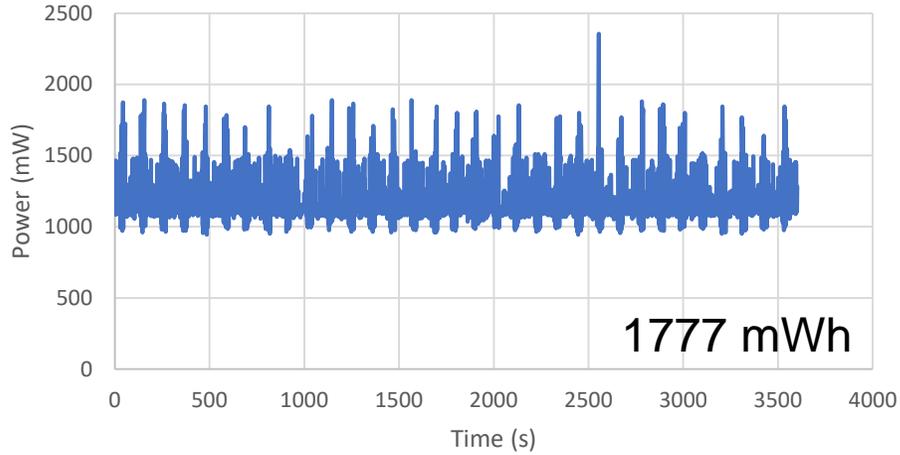


Voltage (V) and Current (mA)

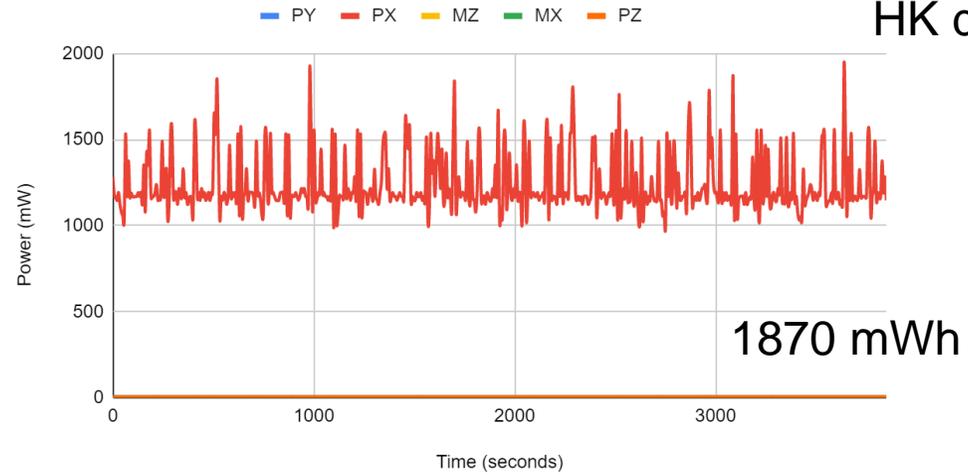


# Test without battery connected (GPS ON, heater OFF)

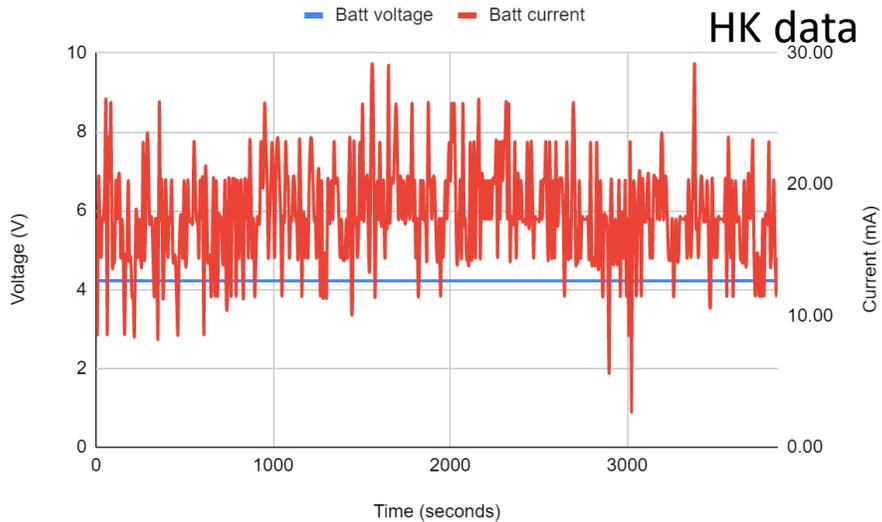
Power consumption (no Battery) Current probe



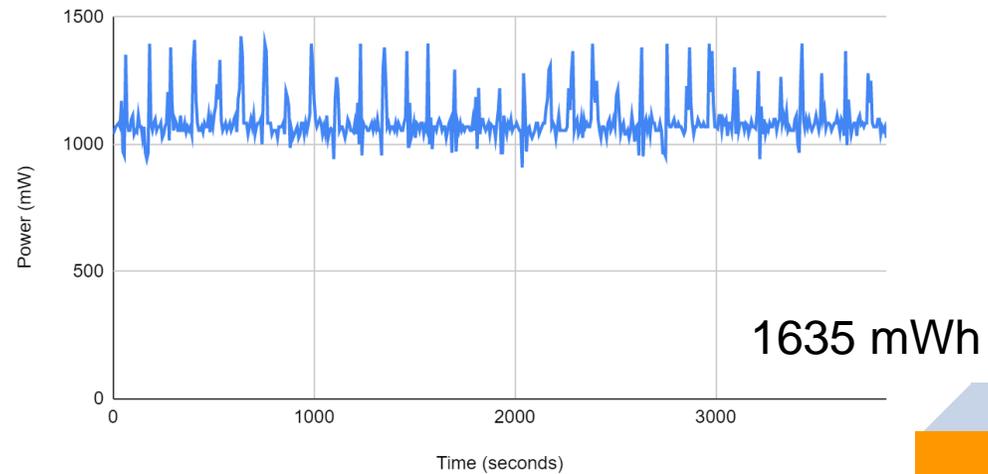
Power Generation



HK data



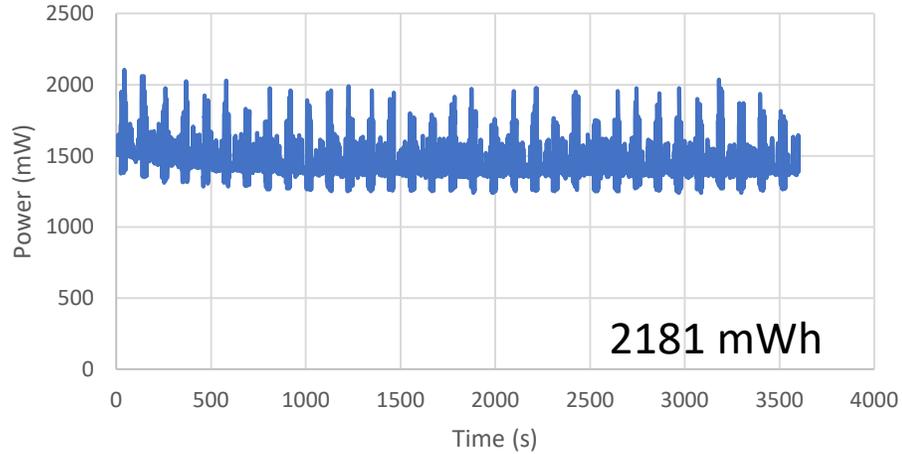
SRC Power Generation



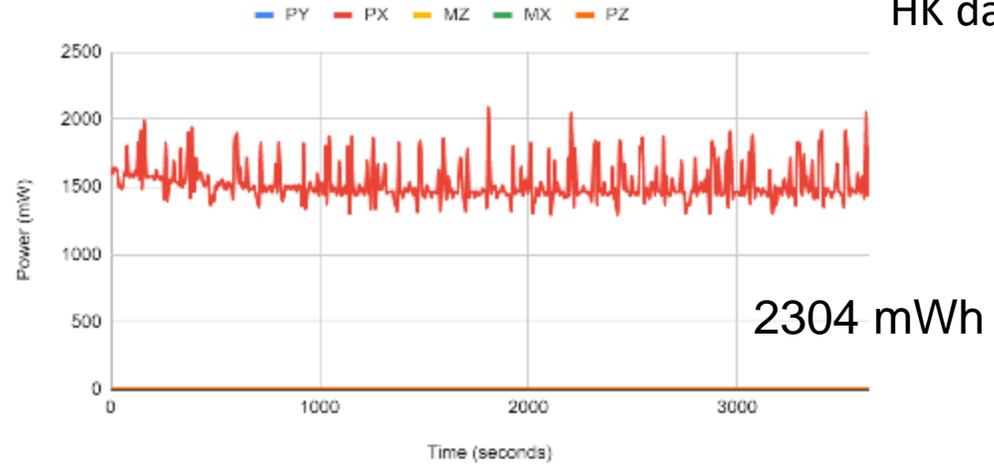
HK data

# Test with battery connected (GPS ON, heater OFF)

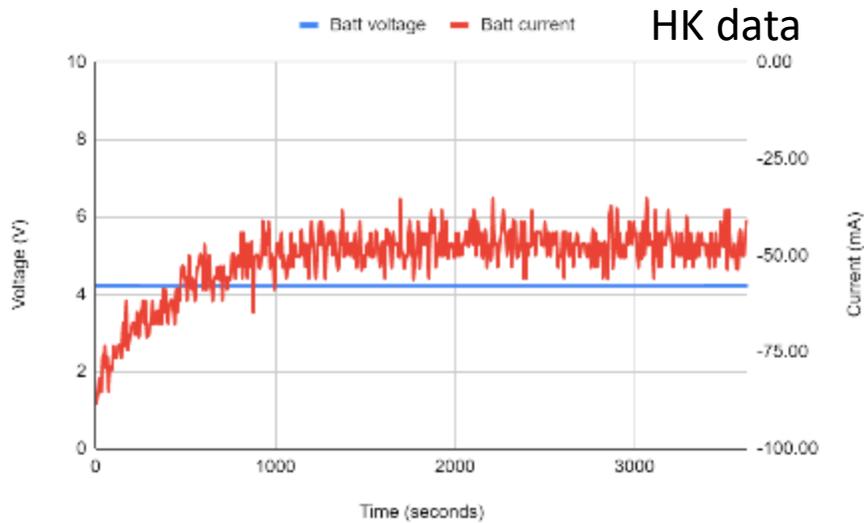
Power consumption (with Battery) Current probe



Power Generation

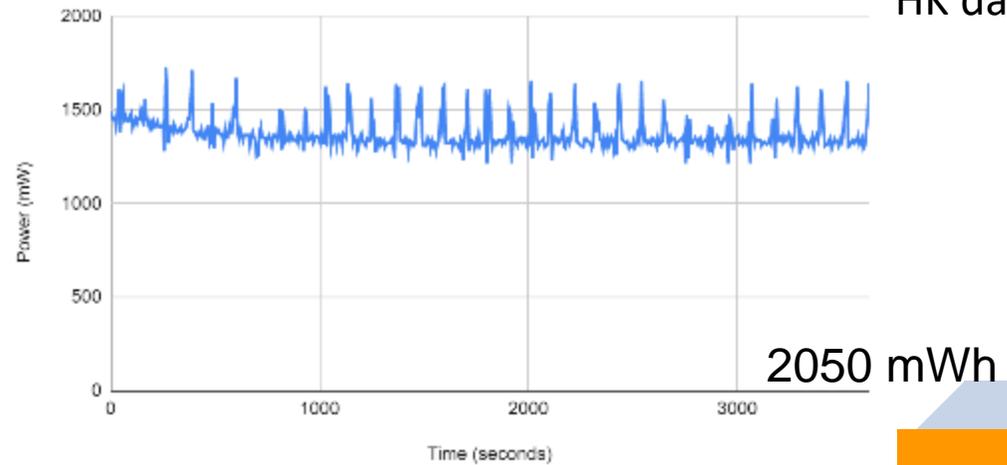


HK data



HK data

SRC Power Generation



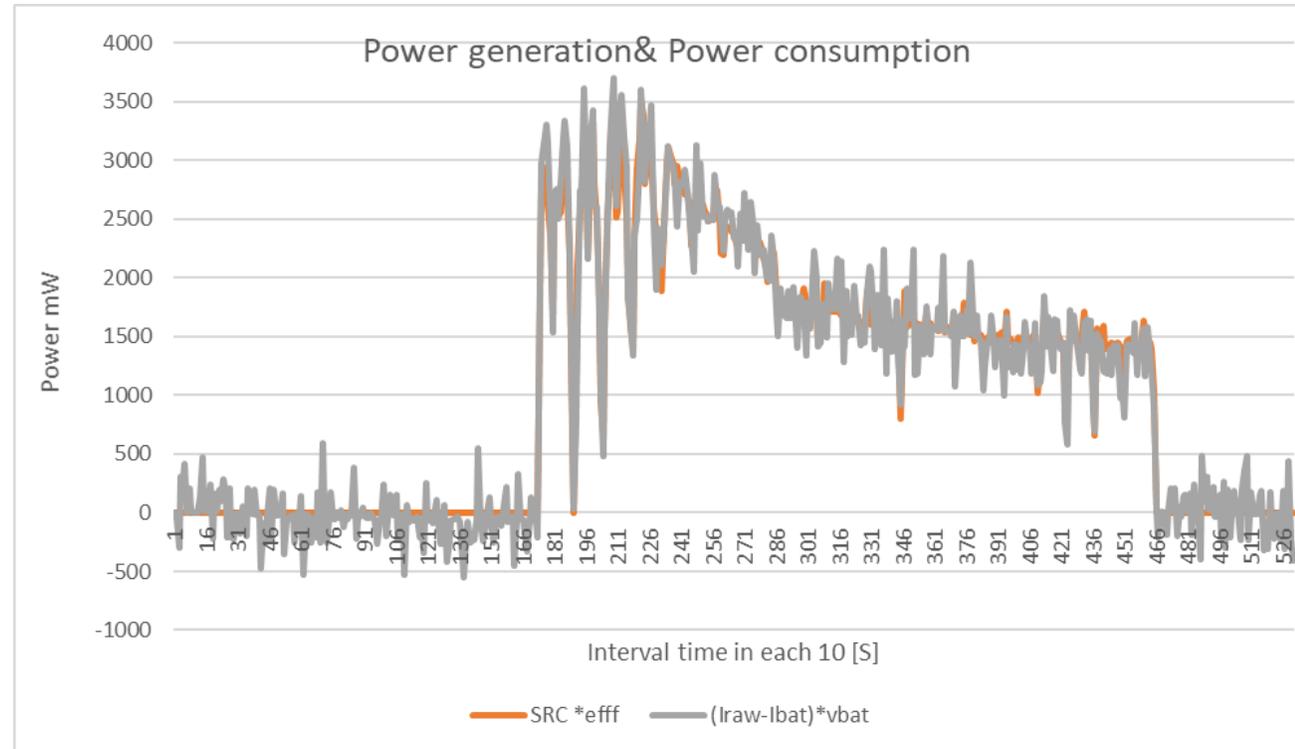
HK data





# Isrc, Iraw & Ibat in the same orbit.

calculate the total power generated using the newly calibrated



$$\text{SRC} * \text{efficiency} = (\text{Iraw} - \text{Ibat}) * \text{Vbat}$$