

Use of BIRDS Open-Source Standardized BUS in Munal, Danfe and Danfe-2

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MUNAL

High School Satellite Consortium



BIRDS Open-Source

Overview

- To demonstrate novel SPDM based COM/OBC designed in-٠ house
- To give continuity and improvement to two Missions of ٠ NepaliSat-1: Store & Forward (S&F) and Imaging Mission

Specifications					
Dimension	1U (100X100X113.5) mm				
Weight	1.051 kg				
Harness	s Backplane Board				
Missions Camera, PACDS, SPDM, Art mission					
OBC : On-Board Computer EPS : Electrical Power Supply					

SPDM : Satellite System on Chip Payload Demonstration Mission

PACDS : Passive Attitude Control and Determination System

Μυνιλ

- In house design, build, test and launch of Nepal's first High • School CubeSat









Orbital characteristics



• Expected launch from PSLV on August 2023

S.N.	Parameters	LEO	SSO*
1.	Inclination	51.64°	97.5 °
2.	Altitude	400 km	550 km
3	Orbital Velocity	7.5 km/sec	7.8km/sec
4.	Period	90 min.	95 min.

LEO: Low Earth Orbit

SSO: Sun-Synchronous Orbit

* Data presented according to previous Missions characteristics



OBC/EPS (Single Board)







OBC/EPS BOARD: EPS (Electrical Power System)



Power Generation				
Cell Type	SolAero Cells			
Cell Efficiency	29.5%			
Electrical Performance	Voc = 2.726 V, Isc = 522mA			
Area 30.4 <i>cm</i> ²				
Azur Space Solar cells on	Azur Space Solar cells on –X Panel.			

Power Storage					
Battery Type	Nickel Metal Hydride Batteries, AA				
Capacity / nominal Voltage	2450 mAh / 1.2 Volts				
Battery Configuration	3S2P				





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Power Budget



Subsystem/ Mission Modes	Power (mW)	Duration (H)	Energy (mWh)
OBC/ EPS	396	1.62	641.52
COM (RX)	170	1.13167	192.3839
COM (TX_CW)	800	0.485	388
COM (TX_Mission)	4200	0.1261	529.62
PACDS	132	1.13167	213.84
SPDM (TX)	389.4	0.485	188.859
SPDM (RX)	115.5	1.13167	130.07
CAM MCU	194.7	0.1832	35.67
Camera(x2)	2370	0.1832	434.14
Antenna Deployment	6720	0.00449077	30.178





Line width 8mm

CN303

CONN SOCKET

CONN SOCKET 4

CN304

Line width 8mm

JUMPER Line width 4mm

BAT_TEMP



- Deployment switch 4 requires external source(Solar Panel) to get triggered initially. Satellite won't start through battery alone.
 - The satellite will not turn on if its deployed in eclipse and only turns

RBF2

RBF2 SRC

RBF2 SINK

U26

GND_SYS

S1 D1-2

3 S2 D2-2 5

G2 D2-1 Si7232DN

G1 D1-1 6



Communication Board (In-house)





5/11/2023





Telemetry and mission data downlink		Command Uplink		CW	Beacon
Downlink Rate	4800bps	Uplink Rate	4800 bps	Data Rate	20wpm
Bandwidth	26KHz	Bandwidth	26KHz	Bandwidth	50Hz
Downlink Frequency	401.375 MHz	Uplink Frequency	402.375 MHz	Frequency	401.375 MHz
Modulation	GFSK	Modulation	GFSK	Modulation	ON/OFF Keying

Uplink data format

Elements	Header	Call sign	Control	PID	Info	Checksum	Footer
Size (bytes)	1	14	1	1	13	2	1

Alternative:

Beacon transmits 1 packet data every two minutes.

Downlink data format

Packet format (AX.25)

Elements	Header	Call sign	Control	PID	Info	Checksum	Footer
Size (bytes)	1	14	1	1	80	2	1



Uplink/ Downlink Budget

Ground Station	Command Uplink GFSK					
TX power [W]	50 (17 [dBw])	50	50	50	50	50
Line Loss [dB]	3	3	3	3	3	3
Antenna Gain [dBi]	22	22	22	22	22	22
GS EIRP [dBw]	37	37	37	37	37	37
		UPLINK	Path		•	
Orbital Altitude [km]	550	550	550	550	550	550
Elevation Angle [degree]	10	15	20	30	60	80
Slant Range [km]	1815.08	1518.02	1293.55	992.78	626.89	557.80
GS Ant. pointing Loss [dB]	1	1	1	1	1	1
Polarization Loss [dB]	3	3	3	3	3	
Path Loss [dB]	149.64	148.09	146.70	144.40	140.41	139.39
Atmohperic Loss	1	1	1	1	1	1
lonospheric Loss	0.4	0.4	0.4	0.4	0.4	0.4
Rain Loss	0	0	0	0	0	(
Isotropic Signal at Satellite [dbW]	-118.04	-116.49	-115.10	-112.80	-108.81	-107.79
		Satellite RX s	ensitivity			
Antenna Pointing Loss	5	5	5	5	5	Ę
Antenna Gain [dBi]	0.9	0.9	0.9	0.9	0.9	0.9
Line Loss [dB]	3	3	3	3	3	~
RX power at LNA input [dBw]	-125.14	-123.59	-122.20	-119.90	-115.91	-114.89
RX power at LNA input [dBm]	-95.14	-93.58	-92.199	-89.9	-85.9	-84.89
Receiver Sensitivity [dB]	-100	-100	-100	-100	-100	-100
Link Margin [dB]	4.86	6.42	7.801	10.1	14.1	15.11

Satellite	Downlink Telemetry
TX Power [W]	0.8 (-1 dBw)
Line Loss [dB]	3
Antenna Gain [dBi]	0.9
Satellite EIRP [dBw]	-3.1
Downlink P	Path
Orbital Altitude [km]	550
Elevation Angle [degree]	10
Slant Range [km]	1815.08
Satellite Ant. pointing Loss [dB]	5
Polarization Loss [dB]	3
Path Loss [dB]	149.64
Atmohperic Loss	1
Ionospheric Loss	0.4
Rain Loss	0
Isotropic Signal at Satellite [dbW]	-162.14
Ground Sta	tion
GS Ant. Pointing Loss [dB]	1
GS Ant. Gain [dBi]	22
GS Total Line loss [dB]	3
GS Effective Noise Temp. [K]	1000
RX Power at GS LNA Input [dBw]	-144.14
GS Receiver Bandwidth [Hz]	12500
GS Receiver Noise [dB]	-127.63
SNR at GS Receiver [dB]	14.5
Required SNR at GS Receiver [dB]	10
System Link Margin [dB]	4.5







Specifications					
Antenna Type	UHF dipole Antenna				
Antenna Length	17.9 cm (one arm)				
Antenna material	SK-85(Carbon Steel)				





Antenna Panel

Antenna Panel's design is similar to BIRDS' design



BPB: Back Plane Board



- 60 pin connectors are used for all the mission boards and EPS/OBC.
- 50 pin connector for COM board (Reference: Addnics COM board ICD)



Boards placement on BPB

Connector Name	No. of Pins	Description
J1-J4	60	OBC/EPS, AB, SPDM/PACDS, CAM
J5	50	COM Board
SP1-SP4	12	Solar Panels
SP5	12	Antenna Panel
SW1-SW3	2	Deployment switch





CAM: Camera Mission

IR

RGB CAMERA



ACE MISSION		
Feature	Specification	
Cameras	OpenMV H7 Plus (RGB & NIR)	
Ground Swath	168*95 km (550km orbit)	
Ground Sampling Distance	131m	
Resolution	1280x720	











Image Classification

Image Segmentation





RGB Image

IR-Image

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PACDS: Passive Attitude Control and Determination





Hysteresis Rod

8

HyMu80

SPDM:



Satellite System-on-Chip Payload Demonstration Mission



- Demonstrate the use of integrated Communication(COM) and On-Board Computer(OBC) subsystem based on novel SSoC for future cubesat missions using LoRa(Long Range) Modulation.
- ARM based Dual Core Processor with Radio
- +22 dBm Transmitting power
- -148 dBm Receiving sensitivity







Art and Culture Mission





Satellite

Long Range Test



NAST Ground Station



Chobhar Hill

Distance: 3.565km Path Loss : 92.97 dB Operating Freq: 435-437MHz [To use BIRDS GS Freq Changed from 401/402 MHz] TX power: 22dBm RX sensitivity: -100dBm

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BIRDS Open-Source



Space Qualification Test : TVT



Satellite Setup for TVT







Functional Test Before TVT



Thermovac Controller

Thermal Vacuum Test: Result





Thermal Cycle Profile during TVT -TC01 -TC02 -TC03 -TC04 -TC05 -TC06 -TC07 -TC08 -60 0 1 2 2 5 5 7 8 8 -10 34 17 18 1.9 201 25 22 28 24 25 26 27 28 29 30 31 32 124 3.2 115 Time(hr)

RoadMap







Danfe Space Mission

Multi Payload CubeSat Platform (MPCP)





Danfe Boards





EM Boards

FM Boards



Overview





Source: Aalto-1, multi-payload CubeSat: Design, integration and launch



Danfe Space Mission





Danfe mission Block Diagram





PX4 on STM32F427



Satellite system on chip



Recovery (0.6h)

FT (0.6h)

Time (hours)

Space Qualification Test



Thermal Vacuum Test at Centum Electronics, Bangalore, India

Electromagnetic Compatibility Test at Khwopa Engineering College, Bhaktapur, Nepal

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Danfe-2 Mission

Payload Hosting Initiative





MOHAMMED BIN RASHID SPACE CENTRE

Danfe-2



- UNOOSA's Access to Space for all: Payload Hosting Initiative project.
- MBRSC'S 12U satellite: (PHISat)
- Munal's OBC/EPS and Danfe Space Mission in a single board. (Modular Design)
- Integrated OBC, EPS and Communication system (Bus system in a single board)
- PDR completed on May 9





Danfe-2 Power Budget



- Sun-synchronous Orbit
- Total Duty cycle provided is 30%

Power Budget			
	Power(W)	Duty Cycle	
Main System	1.005	12%	
HK logging	1.15	6%	
LoRA	1.635	9%	



Thank You